

#### Algebraic Geometry with a view towards applications

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#### Plan for this course

- Lecture I: Algebraic modelling (Kinematics)
- Lecture II: Sampling algebraic varieties: the reach.
- Lecture III: Projective embeddings and Polar classes (classical theory)
- Lecture IV: The Euclidian Distance Degree
- Lecture V: Bottleneck degree



#### **References:**

- D. Eklund the numerical algebraic geometry of bottlenecks. ArXiv
- DR-Eklund-Weinstein The bottleneck degree of a variety. ArXiv









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- At some point it becomes singular (M ≠ {p}).
- Half the black distance is called the *reach* of *M*.
- And the line is called a *bottleneck*.



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- ► Goal: efficient method to compute bottlenecks given defining equations for *X* and *Y*.
- Important subgoal: count bottlenecks. Let β(X, Y) := #isolated bottlenecks, β(X) := β(X, X).



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- A pair of (generic) parallel lines in C<sup>2</sup> have a 1-dimensional family of bottlenecks.





#### Example

let  $X \subseteq \mathbb{C}^2$  be one of the two lines of the isotropic quadric

$$x^{2} + y^{2} = (x + iy)(x - iy) = 0,$$

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- Since  $(i, 1) \perp (i, 1)$ , X is orthogonal to itself,
- ▶ and *X* has one bottleneck, namely *X*.



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#### Remark

For generic curves  $X, Y \subseteq \mathbb{C}^2$  of degree  $d_X$  and  $d_Y$ :

$$\beta(X, Y) < d_X^2 d_Y^2 = EDD(X)EDD(Y)$$



#### Proposition (D. Eklund 2018)

For smooth curves  $X, Y \subseteq \mathbb{C}^n$  in general position of degree  $d_X$  and  $d_Y$  and genus  $g_X$  and  $g_Y$ :

$$eta(X, Y) = (3d_X + 2g_X - 2)(3d_Y + 2g_Y - 2) - |X \cap Y| =$$
  
=  $EDD(X)EDD(Y) - |X \cap Y|.$ 

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General position: transversal intersection with Q

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When Y = {p} is a point not on X, bottlenecks of X and Y reduce to the *normal locus* 

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Considering X = Y

 $\beta(X, Y) =$  isolated bottlenecks of X



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- $EDD(X), EDD(Y) \neq 0$
- X and Y are smooth.
- ► X and Y intersect Q transversely.



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- At t = 0:  $x y \perp T_x X$ ,  $T_y Y$ . That is the line  $\overline{xy}$  is a bottleneck! (If  $x \neq y$ )
- ▶ As  $t : 1 \to 0$  the start points  $(x, y) \in NL_X(p) \times NL_Y(q)$ follow paths in  $\mathbb{C}^n \times \mathbb{C}^n$  to endpoints (x, y) such that  $\overline{xy}$  is a bottleneck or x = y.



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- Can use AG instead, inspired by the EDD computation, in order to give a more general formula for the bottlenecks of X, i.e. β(X, X) = β(X).

$$\beta(X) = EDD(X)^2 - R = (p_0 + \ldots + p_n)^2 - R$$

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• 
$$X \subset \mathbb{P}^N$$
 in general position.





Consider a curve  $\mathcal{C} \subset \mathbb{P}^2$ .



Consider a curve  $C \subset \mathbb{P}^2$ . Bottlenecks (p, q) such that

 $(p,q) \in C \times C \setminus \Delta \text{ and } N_p C = N_q C.$ 

where  $\Delta$  is the diagonal scheme in  $X \times X$ .



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where  $\Delta$  is the diagonal scheme in  $X \times X$ . Consider  $g : C \to (\mathbb{P}^2)^{\vee} = \{ \text{ lines in } \mathbb{P}^2 \}$  assigning the line  $N_pC$  to p

The bottlenecks can be computed via the associated *Double Point Scheme* 



## Concrete algebraic formulation of the ideal of bottlenecks and examples worked out in M2 MADDIE later today



# Assumption

*Q* isotropic quadric in  $\mathbb{P}^N$ .

 $X \subset \mathbb{P}^N$  is in general position (BN regular):

- ► X intersects Q transversally.
- X has only finitely many bottlenecks
- one additional (technical) assumption ...





#### Theorem (DR-Eklund- Weinstein)

Assume X is in general position, then the number of bottlenecks (counted with multiplicity) is given by explicit polynomials in  $P_0, \ldots, P_n$ , h where h id the hyperplane class in  $\mathbb{P}^N$ 



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in particular:

▶ for a curve C in  $\mathbb{P}^2$ :

$$\beta(C)=d^4-4d^2+3d$$

• for a curve C in  $\mathbb{P}^3$ :

$$\beta(C) = p_1^2 + 2d^2 - 3p_1 - 2d$$

▶ for a curve S in P<sup>5</sup>:

 $\beta(S) = (p_0 + p_1 + p_2)^2 + (p_0 + p_1)^2 + d^2 - \deg(3h^2 + 6hp_1 + 12p_1^2 + p_2)$ 

$$p_i = \deg(P_i) = P_i h^{N-i}$$



# the affine case



#### the affine case

Let  $X \subset \mathbb{C}^N$ , let  $\overline{X} \subset \mathbb{P}^N$  be its projective closure. Let  $H_{\infty}$  be the hyperplane at infinity and  $X_{\infty} = \overline{X} \cap H_{\infty}$ .



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# Theorem (DR-Eklund-Weinstein)

Under the previous assumptions (for  $\overline{X}$  and  $X_{\infty}$ ):

$$\beta(\boldsymbol{X}) = \beta(\overline{\boldsymbol{X}}) - \beta(\boldsymbol{X}_{\infty})$$



#### DR-D. Eklund, C. Peterson. Adv. App. Math. 2018

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*I* ideal generated by two general degree 2 elements of J, defining a smooth quartic threefold X containing D.



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	Table:									
	$P_1$	$P_2$	$P_3$	$P_{1}P_{2}$	$P_{1}^{2}D$	$P_2D$	$P_1 D^2$	$D^3$		
degree	8	12	16	24	32	24	32	32		



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$EDD(X) = 40$ and $\beta(X) = ?$										



# SUMMARY

- Sampling can be an efficient method of visualising the variety of solutions of polynomial equations, if we can recover the homology.
- ► Any sample of size ε < reach/2 recovers the homology of the manifold</p>
- An estimate of the reach requires an estimate of the bottleneck degree of the variety.
- The bottleneck can be computed via classical algebraic varieties: The polar classes. Generalizing the EDD.



## Thanks to Maddie and Sascha





It's been fun!

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