Algebraic Geometry with a view towards applications

Sandra Di Rocco, ICTP Trieste

## Plan for this course

- Lecture I: Algebraic modelling (Kinematics)
- Lecture II: Sampling algebraic varieties: the reach.
- Lecture III: Projective embeddings and Polar classes (classical theory)
- Lecture IV: The Euclidian Distance Degree
- Lecture V: Bottleneck degree


## References:

- D. Eklund the numerical algebraic geometry of bottlenecks. ArXiv
- DR-Eklund-Weinstein The bottleneck degree of a variety. ArXiv


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- At some point it becomes singular ( $M \neq\{p\}$ ).
- Half the black distance is called the reach of $M$.
- And the line is called a bottleneck.


## Bottlenecks of algebraic varieties

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- For $(x, y) \in X \times Y$ with $x \neq y$, the line joining $x$ and $y$ is a bottleneck if $(x-y) \perp T_{x} X$ and $(y-x) \perp T_{y} Y$.


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- The special case $X=Y$ is of particular interest (see motivation).
- Goal: efficient method to compute bottlenecks given defining equations for $X$ and $Y$.
- Important subgoal: count bottlenecks. Let $\beta(X, Y):=$ \#isolated bottlenecks, $\beta(X):=\beta(X, X)$.


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- A pair of generic lines $X, Y \subset \mathbb{C}^{2}$ has no bottlenecks.
- A pair of (generic) parallel lines in $\mathbb{C}^{2}$ have a 1-dimensional family of bottlenecks.



## Bottlenecks of algebraic varieties

## Example

let $X \subseteq \mathbb{C}^{2}$ be one of the two lines of the isotropic quadric

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x^{2}+y^{2}=(x+i y)(x-i y)=0
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say $X=\langle(i, 1)\rangle$.

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- Since $(i, 1) \perp(i, 1), X$ is orthogonal to itself,
- and $X$ has one bottleneck, namely $X$.


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Remark
For generic curves $X, Y \subseteq \mathbb{C}^{2}$ of degree $d_{X}$ and $d_{Y}$ :

$$
\beta(X, Y)<d_{X}^{2} d_{Y}^{2}=E D D(X) E D D(Y)
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## Bottlenecks of algebraic varieties

## Proposition (D. Eklund 2018)

For smooth curves $X, Y \subseteq \mathbb{C}^{n}$ in general position of degree $d_{X}$ and $d_{Y}$ and genus $g_{X}$ and $g_{Y}$ :

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\begin{gathered}
\beta(X, Y)=\left(3 d_{X}+2 g_{X}-2\right)\left(3 d_{Y}+2 g_{Y}-2\right)-|X \cap Y|= \\
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Corollary
For generic curves $X, Y \subseteq \mathbb{C}^{2}$ of degree $d_{X}$ and $d_{Y}$ :

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General position: transversal intersection with $Q$
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- When $Y=\{p\}$ is a point not on $X$, bottlenecks of $X$ and $Y$ reduce to the normal locus

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- Considering $X=Y$
$\beta(X, Y)=$ isolated bottlenecks of $X$


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General position means:
- $E D D(X), E D D(Y) \neq 0$
- $X$ and $Y$ are smooth.
- $X$ and $Y$ intersect $Q$ transversely.

A numerical method for bottlenecks

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- At $t=0: x-y \perp T_{x} X, T_{y} Y$. That is the line $\overline{x y}$ is a bottleneck! (If $x \neq y$ )


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- At $t=0: x-y \perp T_{x} X, T_{y} Y$. That is the line $\overline{x y}$ is a bottleneck! (If $x \neq y$ )
- As $t: 1 \rightarrow 0$ the start points $(x, y) \in N L_{X}(p) \times N L_{Y}(q)$ follow paths in $\mathbb{C}^{n} \times \mathbb{C}^{n}$ to endpoints $(x, y)$ such that $\overline{x y}$ is a bottleneck or $x=y$.

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\beta(X)=E D D(X)^{2}-R=\left(p_{0}+\ldots+p_{n}\right)^{2}-R \\
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- $X \subset \mathbb{P}^{N}$ in general position.


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where $\Delta$ is the diagonal scheme in $X \times X$.

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where $\Delta$ is the diagonal scheme in $X \times X$.
Consider $g: C \rightarrow\left(\mathbb{P}^{2}\right)^{\vee}=\left\{\right.$ lines in $\left.\mathbb{P}^{2}\right\}$ assigning the line $N_{p} C$ to $p$

The bottlenecks can be computed via the associated Double Point Scheme

Concrete algebraic formulation of the ideal of bottlenecks and examples worked out in M2 MADDIE later today

## Assumption

$Q$ isotropic quadric in $\mathbb{P}^{N}$.
$X \subset \mathbb{P}^{N}$ is in general position (BN regular):

- $X$ intersects $Q$ transversally.
- X has only finitely many bottlenecks
- one additional (technical) assumption ...

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## Theorem (DR-Eklund- Weinstein)

Assume $X$ is in general position, then the number of bottlenecks (counted with multiplicity) is given by explicit polynomials in $P_{0}, \ldots, P_{n}, h$ where $h$ id the hyperplane class in $\mathbb{P}^{N}$

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in particular:

- for a curve $C$ in $\mathbb{P}^{2}$ :

$$
\beta(C)=d^{4}-4 d^{2}+3 d
$$

- for a curve $C$ in $\mathbb{P}^{3}$ :

$$
\beta(C)=p_{1}^{2}+2 d^{2}-3 p_{1}-2 d
$$

- for a curve $S$ in $\mathbb{P}^{5}$ :

$$
\begin{gathered}
\beta(S)=\left(p_{0}+p_{1}+p_{2}\right)^{2}+\left(p_{0}+p_{1}\right)^{2}+d^{2}-\operatorname{deg}\left(3 h^{2}+6 h p_{1}+12 p_{1}^{2}+p_{2}\right) \\
p_{i}=\operatorname{deg}\left(P_{i}\right)=P_{i} h^{N-i}
\end{gathered}
$$

the affine case

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## the affine case

Let $X \subset \mathbb{C}^{N}$, let $\bar{X} \subset \mathbb{P}^{N}$ be its projective closure. Let $H_{\infty}$ be the hyperplane at infinity and $X_{\infty}=\bar{X} \cap H_{\infty}$.

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Theorem (DR-Eklund-Weinstein)
Under the previous assumptions (for $\bar{X}$ and $X_{\infty}$ ):

$$
\beta(X)=\beta(\bar{X})-\beta\left(X_{\infty}\right)
$$

Polar calculus: example
DR-D. Eklund, C. Peterson. Adv. App. Math. 2018 code for $p_{i}, \operatorname{deg} P_{i} P_{j}$ and $\operatorname{deg}\left(P_{i}^{k} D^{m}\right)$ for any divisor $D$.

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I ideal generated by two general degree 2 elements of $J$, defining a smooth quartic threefold $X$ containing $D$.

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Table:

|  | $P_{1}$ | $P_{2}$ | $P_{3}$ | $P_{1} P_{2}$ | $P_{1}^{2} D$ | $P_{2} D$ | $P_{1} D^{2}$ | $D^{3}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| degree | 8 | 12 | 16 | 24 | 32 | 24 | 32 | 32 |

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$E D D(X)=40$ and $\beta(X)=$ ?

## SUMMARY

- Sampling can be an efficient method of visualising the variety of solutions of polynomial equations, if we can recover the homology.
- Any sample of size $\varepsilon<\frac{\text { reach }}{2}$ recovers the homology of the manifold
- An estimate of the reach requires an estimate of the bottleneck degree of the variety.
- The bottleneck can be computed via classical algebraic varieties: The polar classes. Generalizing the EDD.

Thanks to Maddie and Sascha


It's been fun!

