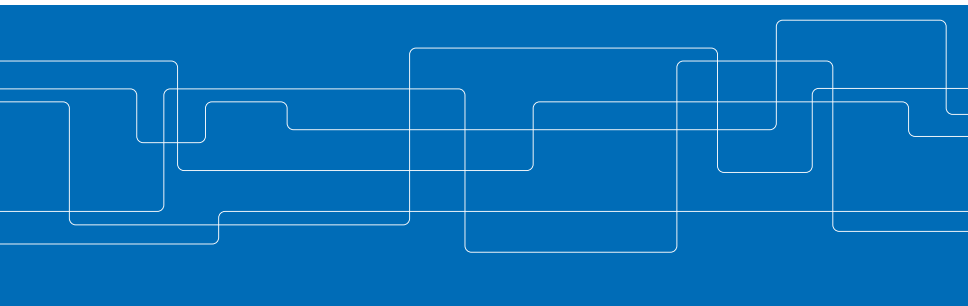


Algebraic Numerics and Sampling:

Algebraic Geometry with a view towards applications

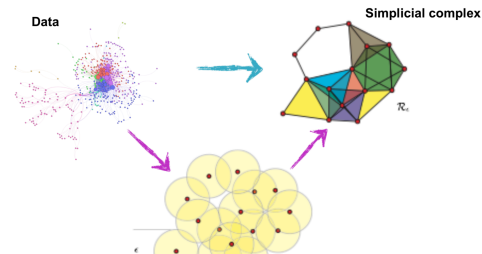
Sandra Di Rocco,

ICTP Trieste



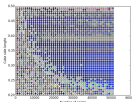
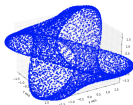
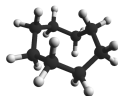
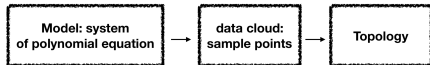
Data analysis

- ▶ Given a data cloud, discover the geometry (shape) of the data. (DATA INTERPOLATION)
- ▶ Given a data cloud, give it a structure and deduce useful information. (TOPOLOGICAL DATA ANALYSIS)



Sampling

We will focus of certain algebraic aspects of data collection coming from algebraic modelling:





Plan for this course

- ▶ Lecture I: Algebraic modelling (Kinematics)
- ▶ Lecture II: Sampling algebraic varieties: the reach.
- ▶ Lecture III: Projective embeddings and Polar classes (classical theory)
- ▶ Lecture IV: The Euclidian Distance Degree (closest point)
- ▶ Lecture V: Bottleneck degree from classical geometry (back to sampling)



***k*-revolute serial chain linkage**



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k -revolute serial chain linkage



a kR chain consists of $k + 1$ rigid links connected with k revolute joints



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Forward Kinematics Problem (FKP): Compute the position of the end-effector, given the joint-angles



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Forward Kinematics Problem (FKP): Compute the position of the end-effector, given the joint-angles

Inverse Kinematics Problem (IKP): Compute the joint-angles taking the mechanism to a specified position of the end-effector



Rigid Body Motion



Rigid Body Motion

A rigid body motion in 3-space is a composition of a rotation and a translation, i.e. an element of $SE_3(\mathbb{R})$, the semi-direct product of \mathbb{R}^3 and $SO_3(\mathbb{R})$.



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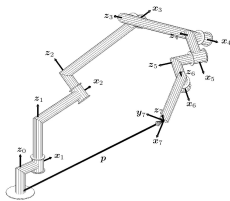
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$Q_\mathbb{R} \subset Q \subset \mathbb{P}^7_\mathbb{C}$

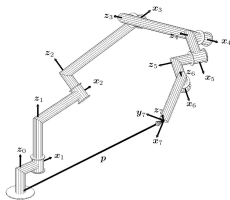


6R-chain

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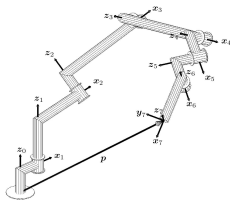


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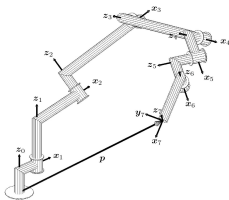
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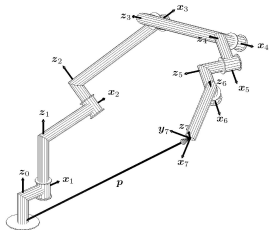


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- ▶ The transformation from hand coordinates to ground coordinates is a function of the $\theta_i \in S^1 \cong \mathbb{P}_{\mathbb{R}}^1$

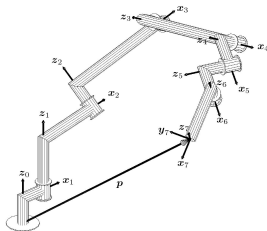


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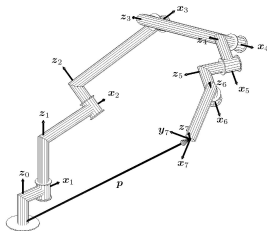
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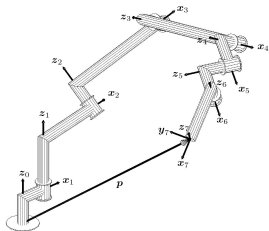


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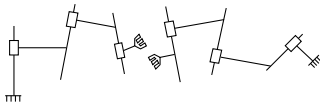
- 1985** Tsai & Morgan proved that the degree of a general fiber is 16
- 1988** Li & Liang Efficient algorithm (16 paths)
- 1988** Algebraic geometry (16 paths)



Intersection theory

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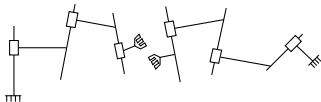
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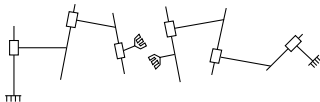


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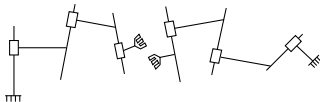
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So the problem is reduced to intersection theory on \mathcal{Q} .



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- ▶ Can be done f.ex via the BB "plus" and "minus" decomposition via a \mathbb{C}^* action.



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- ▶ $U_7 = \{x_0 = \dots = x_6 = 0, x_7 \neq 0\}$ (a point).



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- ▶ Consider the Segre model $F : \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1 \rightarrow \mathcal{Q}$.

$$F(a_0, a_1, b_0, b_1, c_0, c_1) = \begin{pmatrix} a_0 b_0 c_0 \\ a_1 b_1 c_0 \\ a_1 b_0 c_1 \\ a_0 b_1 c_1 \\ a_1 b_0 c_0 \\ a_0 b_1 c_0 \\ -a_0 b_0 c_1 \\ -a_1 b_1 c_1 \end{pmatrix}.$$



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- ▶ Moreover, $\text{Im}F \subset \mathbb{P}^7$ has degree $3! = 6$.
- ▶ Let $h \in A_5(\mathcal{Q})$ be the hyperplane class. Then

$$6 = \deg(h^3[\text{Im}F]) = a \deg(h^3g_1) + b \deg(h^3g_2) = a + b,$$

and hence $b = 2$ and $2ab = 16$.



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Consider the map:

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How can we compute and present its solution?



Visualization

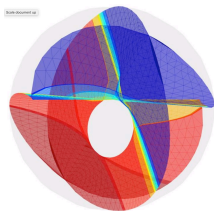


Visualization

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Visualization

- ▶ Currently: Bertini real: D. Brake, Bates-Hauenstein-Sommese-Wampler
- ▶ Cell decomposition of almost smooth real algebraic surfaces
Besana, Di Rocco, Hauenstein, Sommese, Wampler
Numerical Algorithms (2013)



<http://www.bertiniereal.com>



3D printed



Cycloalkane



Cycloalkane

A *cycloalkane* consists only of hydrogen and carbon atoms arranged in a structure containing a single ring (possibly with side chains), and all of the carbon-carbon bonds are single. [Wikipedia]



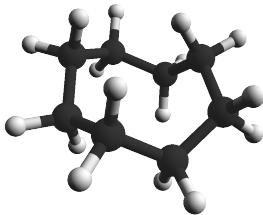
Cycloalkane

A *cycloalkane* consists only of hydrogen and carbon atoms arranged in a structure containing a single ring (possibly with side chains), and all of the carbon-carbon bonds are single. [Wikipedia] The *cyclooctane molecule* for ex. consists of eight carbon atoms in a ring with two hydrogen atoms bound to each carbon atom.



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https://commons.wikimedia.org/wiki/File:Cyclooctane_ballandstick.png.



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 - ▶ n_i : normal direction.
 - ▶ for $i \in \mathbb{Z}_8$, δ_i is the angle between n_i and n_{i+1} .



Cyclo-octane



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- ▶ The cyclo-octane surface permits a whole range of symmetries. Consider the transformation

$$(\delta_0, \delta_1, \delta_2, \delta_3, \delta_4, \delta_5, \delta_6, \delta_7) \mapsto (\delta_4, \delta_5, \delta_6, \delta_7, \delta_0, \delta_1, \delta_2, \delta_3).$$



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- ▶ there is a component, *the spherical component*, pointwise fixed by this transformation, actually contained in a linear subspace $\mathbb{R}^4 \subset \mathbb{R}^8$.
- ▶ *Topology of cyclo-octane energy landscape*, Martin S, Thompson A, Coutsiyas EA, Watson JP. J Chem Phys. 2010. The surface has two components: one with the homology of a sphere and one with the homology of a Klein bottle.



Sampling a cyclo-octane

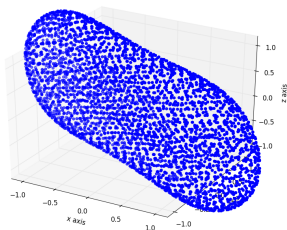


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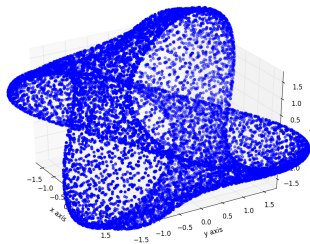
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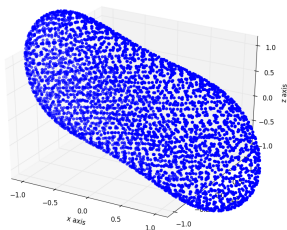
spherical component



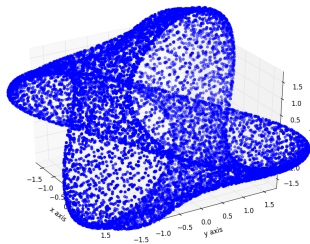
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Klein component

Two irreducible components. The surface is connected!



The complex



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- ▶ Let $r(p)$ in the lattice $\varepsilon\mathbb{Z}^8$ be the **unique closest point** to $p \in E$.
- ▶ Complex:

$$\mathcal{C}(\varepsilon, E) = \bigcup_{p \in E} H(r(p), \varepsilon)$$

where $H(q, \varepsilon)$ is the hypercube in \mathbb{R}^8 centered at q with side length ε .



Invariants



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Homology of the cube complex: $CHomP$

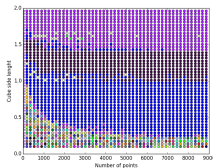
M. Gameiro, T. Gedeon, H. Kokubu, J.-P. Lessard, K. Mischaikow, M. Mrozek, P. Pilarczyk.



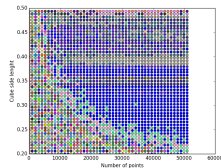
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spherical component

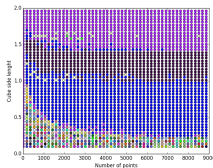


Klein component

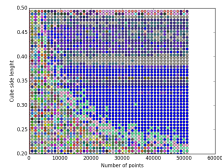
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spherical component



Klein component

Blue corresponding to the homology of a sphere in the case of the spherical component ($H_0 = \mathbb{Z}$, $H_1 = 0$, $H_2 = \mathbb{Z}$) and that of a Klein bottle in the other case ($H_0 = \mathbb{Z}$, $H_1 = \mathbb{Z} \oplus \mathbb{Z}_2$, $H_2 = 0$).



Summary



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- ▶ Algebraic Models
 - ▶ Kinematics
 - ▶ Intersection theory
- ▶ Presenting (visualising) a solution
 - ▶ Numerical methods
 - ▶ Sampling
- ▶ Combining the two approaches: Cycloalkane