

Problem

ReLU networks express **continuous piece-wise affine** functions of their input **x**. To **quantify their expressivity**, the number of linear "pieces", i.e. the **density of linear regions**, has been studied as a proxy for model **nonlinearity**. Intuitively, high nonlinear behaviour requires expressing many regions.

Research Question

Linear region density heavily assumes that all regions **mean**ingfully contribute nonlinearity relevant to learning. Is it the case for **overparameterized** models?

Existing Methods

Prior empirical approaches have been limited to MLPs (Hanin & Rolnick, 2019; Novak et al., 2018) or small ConvNets (Zhang & Wu, 2020). Analytic methods don't scale to modern networks, while numerical ones assume *uniform* density in the input space.

Adaptive Linear Region Discovery



Our fast numerical method finds the smallest $\lambda > 0$ to cross the nearest region boundary, in directions tangent to the "data" ", with a single forward pass. We use it to compute manifold our novel measure of nonlinearity, *absolute deviation*.

Are All Linear Regions Created Equal?

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(1) **Density is** a **noisy** estimator of nonlinearity of large networks. (2) In **model-wise double descent** (Nakkiran et al., 2019), past the noise interpolation threshold, local linearity increases, connecting reduced test error to reduced model nonlinearity.



Ranking Nonlinearity

Capturing Effective Nonlinearity

2019. *ICLR*, 2018.



Density & Variation

Table: Spearman rank correlation between density and absolute deviation.

	CIFAR-10		CIFAR-100
	VGG8	ResNet18	VGG8
vanilla	-0.15 ± 0.00	0.05 ± 0.03	0.00 ± 0.02
augment.	-0.08 ± 0.02	0.17 ± 0.06	0.11 ± 0.08
noise 0.2	0.04 ± 0.02	0.21 ± 0.02	
noise 0.4	0.11 ± 0.02	0.21 ± 0.04	
noise 0.6	0.18 ± 0.07	0.25 ± 0.03	
noise 0.8	0.26 ± 0.04	0.22 ± 0.02	
noise 1.0	0.14 ± 0.04	0.27 ± 0.04	

References

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