## Naïve Bayes Classifier

Lecture 7 (Part I), DD2431 Machine Learning

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- Sensors give measurements which can be converted to features.
- However in the real world



## Samples

because of
$\checkmark$ Measurement noise
$\checkmark$ Intra-class variation
$\checkmark$ Poor choice of features

## Feature Space

End result: a $K$-dimensional space

- in which each dimension is a feature
- containing $n$ labelled samples (objects)

- Size of feature space exponential in number of features.
- More features $\Longrightarrow$ potential for better description of the objects but...
More features $\Longrightarrow$ more difficult to model $P(\mathbf{x} \mid y)$.
- Extreme Solution: Naïve Bayes classifier
$\checkmark$ All features (dimensions) regarded as independent.
$\checkmark$ Model $k$ one-dimensional distributions instead of one $k$-dimensional distribution.


## Naïve Bayes Classifier

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Naïve Bayes Classifier
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- $\mathbf{x}$ is a vector $\left(x_{1}, \ldots, x_{K}\right)$ of attribute or feature values.
- Let $\mathcal{Y}=\{1,2, \ldots, Y\}$ be the set of possible classes.
- The MAP estimate of $y$ is

$$
\begin{aligned}
y_{\text {MAP }} & =\arg \max _{y \in \mathcal{Y}} P\left(y \mid x_{1}, \ldots, x_{K}\right) \\
& =\arg \max _{y \in \mathcal{Y}} \frac{P\left(x_{1}, \ldots, x_{K} \mid y\right) P(y)}{P\left(x_{1}, \ldots, x_{K}\right)} \\
& =\arg \max _{y \in \mathcal{Y}} P\left(x_{1}, \ldots, x_{K} \mid y\right) P(y)
\end{aligned}
$$

- Naïve Bayes assumption: $P\left(x_{1}, \ldots, x_{K} \mid y\right)=\prod_{k=1}^{K} P\left(x_{k} \mid y\right)$
- This give the Naïve Bayes classifier.

$$
y_{\mathrm{MAP}}=\arg \max _{y \in \mathcal{Y}} P(y) \prod_{k=1}^{K} P\left(x_{k} \mid y\right)
$$

- One of the most common learning methods.
- When to use:
$\checkmark$ Moderate or large training set available.
$\checkmark$ Features $x_{i}$ of a data instance $\mathbf{x}$ are conditionally independent given classification (or at least reasonably independent, still works with a little dependence).
- Successful applications:
$\checkmark$ Medical diagnoses (symptoms independent)
$\checkmark$ Classification of text documents (words independent)


## Example: Play Tennis?

What I did in the past:

| outlook | temp. | humidity | windy | play | outlook | temp. | humidity | windy | play |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| sunny | hot | high | false | no | sunny | mild | high | false | no |
| sunny | hot | high | true | no | sunny | cod | normal | false | yes |
| overcast | hot | high | false | yes | rainy | mild | normal | false | yes |
| rainy | mild | high | fake | yes | sunny | mild | normal | true | yes |
| rainy | cool | normal | fake | yes | overcast | mild | high | true | yes |
| rainy | cool | normal | true | no | overcast | hot | normal | false | yes |
| overcast | cool | normal | true | yes | rainy | mild | high | true | no |

Counts of when I played tennis (did not play)

| Outlook |  |  | Temperature |  |  | Humidity |  | Windy |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| sunny | overcast | rain | hot | mild | cool | high | normal | false | true |
| 2 (3) | 4 (0) | 3 (2) | 2 (2) | 4 (2) | 3 (1) | 3 (4) | 6 (1) | 6 (2) | 3 (3) |

Prior of whether I played tennis or not

$$
\text { Counts: } \quad \text { Prior Probabilities: }
$$

Likelihood of attribute when tennis played $P\left(x_{i} \mid \mathrm{y}=\mathrm{yes}\right)\left(P\left(x_{i} \mid \mathrm{y}=\mathrm{no}\right)\right)$

| Outlook |  |  | Temperature |  |  | Humidity |  | Windy |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| sunny | overcast | rain | hot | mild | cool | high | normal | false | true |
| $\frac{2}{9}\left(\frac{3}{5}\right)$ | $\frac{4}{9}\left(\frac{0}{5}\right)$ | $\frac{3}{9}\left(\frac{2}{5}\right)$ | $\frac{2}{9}\left(\frac{2}{5}\right)$ | $\frac{4}{9}\left(\frac{2}{5}\right)$ | $\frac{3}{9}\left(\frac{1}{5}\right)$ | $\frac{3}{9}\left(\frac{4}{5}\right)$ | $\frac{6}{9}\left(\frac{1}{5}\right)$ | $\frac{6}{9}\left(\frac{2}{5}\right)$ | $\frac{3}{9}\left(\frac{3}{5}\right)$ |

## Naïve Bayes: Independence Violation

- Conditional independence assumption:

$$
P\left(x_{1}, x_{2}, \ldots, x_{K} \mid y\right)=\prod_{k=1}^{K} P\left(x_{k} \mid y\right)
$$

often violated - but it works surprisingly well anyway!

- Note: Do not need the posterior probabilities $P(y \mid \mathbf{x})$ to be correct. Only need $y_{\text {MAP }}$ to be correct.
- Since dependencies ignored, naïve Bayes posteriors often unrealistically close to 0 or 1 .
Different attributes say the same thing to a higher degree than we expect as they are correlated in reality.

Inference: Use the learnt model to classify a new instance.

## New instance:

$$
\mathbf{x}=(\text { sunny }, \text { cool }, \text { high, true })
$$

## Apply Naïve Bayes Classifier:

$$
y_{\mathrm{MAP}}=\arg \max _{y \in\{\text { yes, no }\}} P(y) \prod_{i=1}^{4} P\left(x_{i} \mid y\right)
$$

$P($ yes $) P\left(\right.$ sunny | yes) $P\left(\right.$ cool | yes) $P\left(\right.$ high $\mid$ yes) $P\left(\right.$ true | yes) $=\frac{9}{14} \times \frac{2}{9} \times \frac{3}{9} \times \frac{3}{9} \times \frac{3}{9}=.005$ $P($ no $) P($ sunny $\mid$ no $) P($ cool $\mid$ no $) P($ high $\mid$ no $) P($ true $\mid$ no $)=\frac{5}{14} \times \frac{3}{5} \times \frac{1}{5} \times \frac{4}{5} \times \frac{3}{5}=.021$
$\Longrightarrow y_{\mathrm{MAP}}=\mathrm{no}$

## Naïve Bayes: Estimating Probabilities

- Problem: What if none of the training instances with target value $y$ have attribute $x_{i}$ ? Then

$$
P\left(x_{i} \mid y\right)=0 \quad \Longrightarrow \quad P(y) \prod_{i=1}^{K} P\left(x_{i} \mid y\right)=0
$$

- Solution: Add as prior knowledge that $P\left(x_{i} \mid y\right)$ must be larger than 0 :

$$
P\left(x_{i} \mid y\right)=\frac{n_{y}+m p}{n+m}
$$

where
$n=$ number of training samples with label $y$
$n_{y}=$ number of training samples with label $y$ and value $x_{i}$
$p=$ prior estimate of $P\left(x_{i} \mid y\right)$
$m=$ weight given to prior estimate (in relation to data)

## Example: Spam detection

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Example: Spam detection
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- Aim: Build a classifier to identify spam e-mails.


## - How:

Training
$\checkmark$ Create dictionary of words and tokens $\mathcal{W}=\left\{w_{1}, \ldots, w_{L}\right\}$. These words should be those which are specific to spam or non-spam e-mails.
$\checkmark$ E-mail is a concatenation, in order, of its words and tokens: $\mathbf{e}=\left(e_{1}, e_{2}, \ldots, e_{K}\right)$ with $e_{i} \in \mathcal{W}$.
$\checkmark$ Must model and learn $P\left(e_{1}, e_{2}, \ldots, e_{K} \mid\right.$ spam $)$ and $P\left(e_{1}, e_{2}, \ldots, e_{K} \mid\right.$ not spam $)$


Concatenate words from e-mail into a vector
Inference
$\checkmark$ Given an e-mail, $E$, compute $\mathbf{e}=\left(e_{1}, \ldots, e_{K}\right)$.
$\checkmark$ Use Bayes' rule to compute

$$
P\left(\text { spam } \mid e_{1}, \ldots, e_{K}\right) \propto P\left(e_{1}, \ldots, e_{K} \mid \text { spam }\right) P(\text { spam })
$$

## Example: Spam detection

## Learning:

Assume one has $n$ training e-mails and their labels - spam /non-spam

$$
\mathcal{S}=\left\{\left(\mathbf{e}_{1}, y_{1}\right), \ldots,\left(\mathbf{e}_{n}, y_{n}\right)\right\}
$$

Note: $\mathbf{e}_{i}=\left(e_{i 1}, \ldots, e_{i K_{i}}\right)$.

## Create dictionary

(1) Make a union of all the distinctive words and tokens in $\mathbf{e}_{1}, \ldots, \mathbf{e}_{n}$ to create $\mathcal{W}=\left\{w_{1}, \ldots, \boldsymbol{W}_{L}\right\}$. (Note: words such as and, the, $\ldots$ omitted)

## Learn probabilities

For $y \in\{$ spam, not spam $\}$
(1) Set $P(y)=\frac{\sum_{i=1}^{n} \operatorname{Ind}\left(y_{i}=y\right)}{n}$
-proportion of e-mails from class $y$
(2) $n_{y}=\sum_{i=1}^{n} K_{i} \times \operatorname{Ind}\left(y_{i}=y\right) \leftarrow$ total $\#$ of words in the class $y$ e-mails.
(3) For each word $w_{l}$ compute
$n_{y l}=\sum_{i=1}^{n} \operatorname{Ind}\left(y_{i}=y\right) \times\left(\sum_{k=1}^{K_{i}} \operatorname{Ind}\left(e_{i k}=w_{l}\right)\right) \leftarrow \#$ of occurrences of word $w_{l}$ in the class $y$ e-mails.
(4) $P\left(w_{l} \mid y\right)=\frac{n_{y l}+1}{n_{y}+|\mathcal{W}|}$
$\leftarrow$ assume prior value of $P\left(w_{l} \mid y\right)$ is $1 /|\mathcal{W}|$.

