

# Cubics Minimize Acceleration

## Theorem:

- Given  $n$  data points  $(y_i, t_i)$  to interpolate and fixed end conditions (either prescribed 1st derivative, or zero second derivative), a piecewise cubic interpolant

minimizes the energy:  $E(f) = \int_0^n f''(t)^2 dt$

- This means: A cubic spline curve has the least square acceleration.
- Related to elastic energy: Hooke's elastic energy of a straight line is given by:  $E(\mathbf{f}) = \int_0^n \lambda \|\kappa_2[\mathbf{f}](t)\|^2 dt$
- I.e.: cubic spline interpolation approximates elastic beams.

# Proof: Cubics Minimize Acceleration

Cubic spline:  $c(t)$

Another  $C^2$  interpolating curve:  $a(t)$

Residual:  $d(t) = a(t) - c(t)$ .

**Energy functional:**

$$\begin{aligned} E(a) &= \int_0^n a''(t)^2 dt \\ &= \int_0^n [c''(t) + d''(t)]^2 dt \\ &= \int_0^n c''(t)^2 dt + 2 \int_0^n c''(t)d''(t)dt + \int_0^n d''(t)^2 dt \end{aligned}$$

# Proof: Cubics Minimize Acceleration

Cubic spline:  $c(t)$

Another  $C^2$  interpolating curve:  $a(t)$

Residual:  $d(t) = a(t) - c(t)$ .

Integration by parts:

$$\int_a^b a(t)b'(t)dt = [a(t)b(t)]_{t=a}^{t=b} - \int_a^b a'(x)b(x)dt$$

Energy functional:

$$E(a) = \int_0^n c''(t)^2 dt + 2 \int_0^n c''(t)d''(t)dt + \int_0^n d''(t)^2 dt$$

Integration by parts:

$$\begin{aligned} \int_0^n c''(t)d''(t)dt &= [c''(t)d'(t)]_0^n - \int_0^n c'''(t)d'(t)dt \\ &= [c''(t)(a'(t) - c'(t))]_{t=0}^{t=n} - \int_0^n c'''(t)d'(t)dt \\ &= \underbrace{c''(n)}_{\substack{0 \text{ for} \\ c''(n)=0}} \underbrace{(a'(n) - c'(n))}_{\substack{0 \text{ if identical first} \\ \text{order end cond.}}} - \underbrace{c''(0)}_{\substack{0 \text{ for} \\ c''(n)=0}} \underbrace{(a'(0) - c'(0))}_{\substack{0 \text{ if identical first} \\ \text{order end cond.}}} - \int_0^n c'''(t)d'(t)dt \end{aligned}$$

# Proof: Cubics Minimize Acceleration

Cubic spline:  $c(t)$

Another  $C^2$  interpolating curve:  $a(t)$

Residual:  $d(t) = a(t) - c(t)$ .

Integration by parts:

$$\int_a^b a(t)b'(t)dt = [a(t)b(t)]_{t=a}^{t=b} - \int_a^b a'(x)b(x)dt$$

Energy functional:

$$E(a) = \int_0^n c''(t)^2 dt + 2 \int_0^n c''(t)d''(t)dt + \int_0^n d''(t)^2 dt$$

Middle term (cont.):

$$\begin{aligned} \int_0^n c''(t)d''(t)dt &= \int_0^n \underbrace{c'''(t)}_{\text{piecewise const.}} d'(t)dt \\ &= \sum_{i=0}^{n-1} c'''(i+0.5) \underbrace{[d(t)]_{t=i}^{t=i+1}}_{=0 \text{ (interpolation)}} \\ &= 0 \end{aligned}$$

# Proof: Cubics Minimize Acceleration

Cubic spline:  $c(t)$

Another  $C^2$  interpolating curve:  $a(t)$

Residual:  $d(t) = a(t) - c(t)$ .

**Energy functional:**

$$E(a) = \underbrace{\int_0^n c''(t)^2 dt}_{\text{cubic spline}} + \underbrace{\int_0^n d''(t)^2 dt}_{\text{additional energy: positive}}$$

**Positive additional energy:**

Any function that differs in second derivative from  $c$  will have higher energy.

$\Rightarrow c$  is a minimal function in terms of  $E$ .