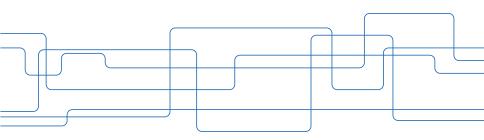


### Lecture 5

# Ch. 5, Norms for vectors and matrices

Emil Björnson/Magnus Jansson/Mats Bengtsson April 27, 2016





## Norms for vectors and matrices — Why?

Problem: Measure size of vector or matrix.

What is "small" and what is "large"?

**Problem:** Measure distance between vectors or matrices. When are they "close together" or "far apart"?

Answers are given by norms.

Also: Tool to analyze convergence and stability of algorithms.



#### Vector norm — axiomatic definition

**Definition:** Let V be a vector space over a field F (R or C).

A function 
$$||\cdot||:V\to \mathbf{R}$$
 is a vector norm if for all  $x,y\in V$ 

(1) 
$$||x|| \ge 0$$
 nonnegative

(1a) 
$$||x|| = 0$$
 iff  $x = 0$  positive

(2) 
$$||cx|| = |c| ||x||$$
 for all  $c \in \mathbf{F}$  homogeneous

(3) 
$$||x+y|| \le ||x|| + ||y||$$
 triangle inequality

A function not satisfying (1a) is called a vector seminorm.

Interpretation: Size/length of vector.



#### Inner product — axiomatic definition

**Definition:** Let V be a vector space over a field F (R or C).

A function  $\langle \cdot, \cdot \rangle : V \times V \to \mathbf{F}$  is an inner product if for all  $x, y, z \in V$ ,

(1) 
$$\langle x, x \rangle \geq 0$$

nonnegative

(1a) 
$$\langle x, x \rangle = 0$$
 iff  $x = 0$ 

positive additive

(2) 
$$\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$$
  
(3)  $\langle cx, y \rangle = c \langle x, y \rangle$  for all  $c \in F$ 

homogeneous

(4) 
$$\langle x, y \rangle = \overline{\langle y, x \rangle}$$

Hermitian property

Interpretation: "Angle" (distance) between vectors.



## Connections between norm and inner products

**Corollary:** If  $\langle \cdot, \cdot \rangle$  is an inner product, then  $||x|| = (\langle x, x \rangle)^{1/2}$  is a vector norm.

Called: Vector norm derived from an inner product. Satisfies parallelogram identity (Necessary and sufficient condition):

$$\frac{1}{2}(||x+y||^2 + ||x-y||^2) = ||x||^2 + ||y||^2$$

Theorem (Cauchy-Schwarz inequality):

$$|\langle x, y \rangle|^2 \le \langle x, x \rangle \langle y, y \rangle$$

We have equality iff x = cy for some  $c \in F$  (i.e., linearly dependent)



### **Examples**

▶ The Euclidean norm  $(l_2)$  on  $\mathbb{C}^n$ :

$$||x||_2 = (|x_1|^2 + |x_2|^2 + \cdots + |x_n|^2)^{1/2}.$$

▶ The sum norm  $(I_1)$ , also called one-norm or Manhattan norm:

$$||x||_1 = |x_1| + |x_2| + \cdots + |x_n|.$$

▶ The max norm  $(I_{\infty})$ :

$$||x||_{\infty} = \max\{|x_1|, |x_2|, \dots, |x_n|\}$$

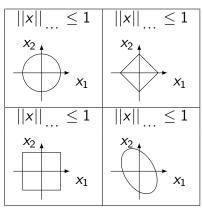
The sum and max norms cannot be derived from an inner product!



#### Unit balls for different norms

The shape of the unit ball characterizes the norm.

Fill in which norm corresponds to which unit ball!



**Properties:** Convex and compact (for finite dimensions), includes the origin.



### Examples cont'd

▶ The  $I_p$ -norm on  $\mathbb{C}^n$  is  $(p \ge 1)$ :

$$||x||_p = (|x_1|^p + |x_2|^p + \dots + |x_n|^p)^{1/p}$$

Norms may also be constructed from others, e.g.,:

$$||x|| = \max\{||x||_{p_1}, ||x||_{p_2}\}$$

or let nonsingular  $T \in M_n$  and  $||\cdot||$  be a given, then

$$||x||_T = ||Tx||.$$

(same notation sometimes used for  $||x||_W = x^* Wx$ )

 Norms on infinite-dimensional vector spaces (e.g., all continuous functions on an interval [a, b]): "similarly" defined (sums become integrals)



### Convergence

**Assume:** Vector space *V* over **R** or **C**.

**Definition:** The sequence  $\{x^{(k)}\}$  of vectors in V converges to

 $x \in V$  with respect to  $||\cdot||$  iff

$$||x^{(k)} - x|| \to 0$$
 as  $k \to \infty$ .

#### Infinite dimension:

- Sequence can converge in one norm, but not another.
- Important to state choice of norm.



### Convergence: Finite dimension

Corollary: For any vector norms  $||\cdot||_{\alpha}$  and  $||\cdot||_{\beta}$  on a finite-dimensional V, there exists  $0 \le C_m < C_M < \infty$  such that

$$C_m||x||_{\alpha} \le ||x||_{\beta} \le C_M||x||_{\alpha} \quad \forall x \in V$$

**Conclusion:** Convergence in one norm ⇒ convergence in all norms.

Note: Result also holds for **pre-norms**, without the triangle inequality.

**Definition:** Two norms are **equivalent** if convergence in one of the norms always implies convergence in the other.

**Conclusion:** All norms are equivalent in the finite dimensional case.



### Convergence: Cauchy sequence

**Definition:** A sequence  $\{x^{(k)}\}$  in V is a Cauchy sequence with respect to  $||\cdot||$  if for every  $\epsilon>0$  there is a  $N_{\epsilon}>0$  such that

$$||x^{(k_1)} - x^{(k_2)}|| \le \epsilon$$

for all  $k_1, k_2 \geq N_{\epsilon}$ .

**Theorem:** A sequence  $\{x^{(k)}\}$  in a finite dimensional V converges to a vector in V iff it is a Cauchy sequence.



#### **Dual norms**

**Definition:** The dual norm of  $\|\cdot\|$  is

$$\|y\|^D = \max_{x:\|x\|=1} \operatorname{Re} y^* x = \max_{x:\|x\|=1} |y^* x| = \max_{x \neq 0} \frac{|y^* x|}{\|x\|}$$

Examples:	Norm	Dual norm
	$\ \cdot\ _2$	$\ \cdot\ _2$
	$\ \cdot\ _1$	$\ \cdot\ _{\infty}$
	$\ \cdot\ _{\infty}$	$\ \cdot\ _1$

- ▶ Dual of dual norm is the original norm.
- Euclidean norm is its own dual.
- ▶ Generalized Cauchy-Schwarz:  $|y^*x| \le ||x|| ||y||^D$



### Vector norms applied to matrices

 $M_n$  is a vector space (of dimension  $n^2$ )

Conclusion: We can apply vector norms to matrices.

**Examples:** The  $I_1$  norm:  $||A||_1 = \sum_{i,j} |a_{ij}|$ .

The  $l_2$  norm (Euclidean/Frobenius norm):

$$||A||_2 = \left(\sum_{i,j} |a_{ij}|^2\right)^{1/2}$$
.

The  $I_{\infty}$  norm:  $||A||_{\infty} = \max_{i,j} |a_{ij}|$ .

Observation: Matrices have certain properties (e.g., multiplication).

May be useful to define particular matrix norms.



#### Matrix norm — axiomatic definition

**Definition:**  $||| \cdot ||| : M_n \to \mathbb{R}$  is a matrix norm if for all  $A, B \in M_n$ ,

(1) 
$$|||A||| \ge 0$$
 nonnegative (1a)  $|||A||| = 0$  iff  $A = 0$  positive

(2) 
$$|||cA||| = |c| |||A|||$$
 for all  $c \in \mathbf{C}$  homogeneous

(3) 
$$|||A + B||| \le |||A||| + |||B|||$$
 triangle inequality  
(4)  $|||AB||| \le |||A||| |||B|||$  submultiplicative

Observations: ► All vector norms satisfy (1)-(3), some may satisfy (4).

► Generalized matrix norm if not satisfying (4).



#### Which vector norms are matrix norms?

 $||A||_1$  and  $||A||_2$  are matrix norms.

 $||A||_{\infty}$  is not a matrix norm (but a generalized matrix norm).

However,  $|||A||| = n||A||_{\infty}$  is a matrix norm.



#### Induced matrix norms

**Definition:** Let  $||\cdot||$  be a vector norm on  $\mathbb{C}^n$ . The matrix norm

$$|||A||| = \max_{||x||=1} ||Ax||$$

is **induced** by  $||\cdot||$ .

**Properties** of induced norms  $||| \cdot |||$ :

- ► |||/||| = 1.
- The only matrix norm N(A) with N(A) ≤ |||A||| for all A ∈ M<sub>n</sub> is N(·) = |||·|||.

Last property called minimal matrix norm.



## **Examples**

The maximum column sum (induced by  $l_1$ ):

$$|||A|||_1 = \max_j \sum_i |a_{ij}|$$

The spectral norm (induced by  $l_2$ ):

$$|||A|||_2 = \max\{\sqrt{\lambda} : \lambda \in \sigma(A^*A)\}$$

The maximum row sum (induced by  $I_{\infty}$ ):

$$|||A|||_{\infty} = \max_{i} \sum_{i} |a_{ij}|$$



## Application: Computing Spectral radius

**Recall:** Spectral radius:  $\rho(A) = \max\{|\lambda| : \lambda \in \sigma(A)\}.$ 

Not a matrix norm, but very related.

**Theorem:** For any matrix norm  $||| \cdot |||$  and  $A \in M_n$ ,

$$\rho(A) \leq |||A|||.$$

**Lemma:** For any  $A \in M_n$  and  $\epsilon > 0$ , there is  $||| \cdot |||$  such that

$$\rho(A) \le |||A||| \le \rho(A) + \epsilon$$

Corollary: For any matrix norm  $||| \cdot |||$  and  $A \in M_n$ ,

$$\rho(A) = \lim_{k \to \infty} |||A^k|||^{1/k}$$



# Application: Convergence of $A^k$

**Lemma:** If there is a matrix norm with |||A||| < 1 then  $\lim_{k \to \infty} A^k = 0$ .

**Theorem:**  $\lim_{k\to\infty} A^k = 0$  iff  $\rho(A) < 1$ .

Matrix extension of  $\lim_{k\to\infty} x^k = 0$  iff |x| < 1.



## Application: Power series

**Theorem:**  $\sum_{k=0}^{\infty} a_k A^k$  converges if there is a matrix norm such that  $\sum_{k=0}^{\infty} |a_k| |||A|||^k$  converges.

Corollary: If |||A||| < 1 for some matrix norm, then I - A is invertible and

$$(I-A)^{-1} = \sum_{k=0}^{\infty} A^k$$

Matrix extension of  $(1-x)^{-1} = \sum_{k=0}^{\infty} x^k$  for |x| < 1.

Useful to compute "error" between  $A^{-1}$  and  $(A + E)^{-1}$ .



### Unitarily invariant and condition number

**Definition:** A matrix norm is unitarily invariant if |||UAV||| = |||A||| for all  $A \in M_n$  and all unitary matrices  $U, V \in M_n$ .

**Examples:** Frobenius norm  $||\cdot||_2$  and spectral norm  $|||\cdot|||_2$ .

**Definition: Condition number for matrix inversion** with respect to the matrix norm  $|||\cdot|||$  of nonsingular  $A \in M_n$  is

$$\kappa(A) = |||A^{-1}||| |||A|||$$

Frequently used in perturbation analysis in numerical linear algebra.

**Observation:**  $\kappa(A) \ge 1$  (from submultiplicative property).

**Observation:** For unitarily invariant norms:  $\kappa(UAV) = \kappa(A)$ .