

$$\begin{aligned} m\ddot{y} &= -mg & \Rightarrow & \quad \dot{y} = -gt + c_1 & \text{B.V.} \Rightarrow & \quad c_1 = v_0 \sin \alpha \\ m\ddot{x} &= 0 & & \quad \dot{x} = c_2 & & \quad c_2 = v_0 \cos \alpha \end{aligned}$$

$$\begin{aligned} \dot{y} &= -gt + v_0 \sin \alpha & \Rightarrow & \quad y = -\frac{1}{2}gt^2 + v_0 \sin \alpha t + c_3 \\ \dot{x} &= v_0 \cos \alpha & & \quad x = v_0 \cos \alpha t + c_4 \end{aligned}$$

$$\text{B.V.} \begin{cases} t=0 \\ x=y=0 \end{cases} \Rightarrow c_3 = c_4 = 0$$

$$\begin{aligned} y &= -\frac{1}{2}gt^2 + v_0 \sin \alpha t & \text{I B:} & \quad x = a \\ x &= v_0 \cos \alpha t & & \quad y = b \\ & & & \quad \dot{y} = 0 \end{aligned}$$

$$0 = -gt + v_0 \sin \alpha \quad (1)$$

$$(1) \Rightarrow t = \frac{v_0 \sin \alpha}{g}$$

$$b = -\frac{1}{2}gt^2 + v_0 \sin \alpha t \quad (2)$$

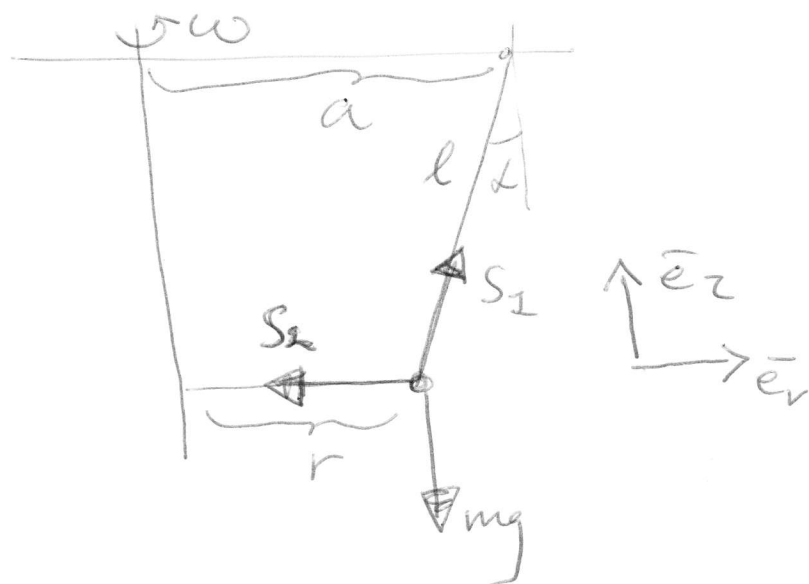
Insatt i (2) och (3) ger

$$a = v_0 \cos \alpha t \quad (3)$$

$$\left. \begin{aligned} b &= \frac{1}{2} \frac{v_0^2 \sin^2 \alpha}{g} \\ a &= \frac{v_0^2 \sin \alpha \cos \alpha}{g} \end{aligned} \right\} \Rightarrow \frac{b}{a} = \frac{1}{2} \tan \alpha \Rightarrow$$

$$\tan \alpha = 2 \frac{b}{a} \quad \alpha = \arctan \left( \frac{2b}{a} \right)$$

2.



$$\bar{e}_r: m(\ddot{r} - r\dot{\theta}^2) = -S_2 + S_1 \sin \alpha \quad (1)$$

$$\bar{e}_z: 0 = S_1 \cos \alpha - mg \quad (2)$$

$$\ddot{r} = 0; \quad r = a - l \sin \alpha; \quad \dot{\theta} = \omega$$

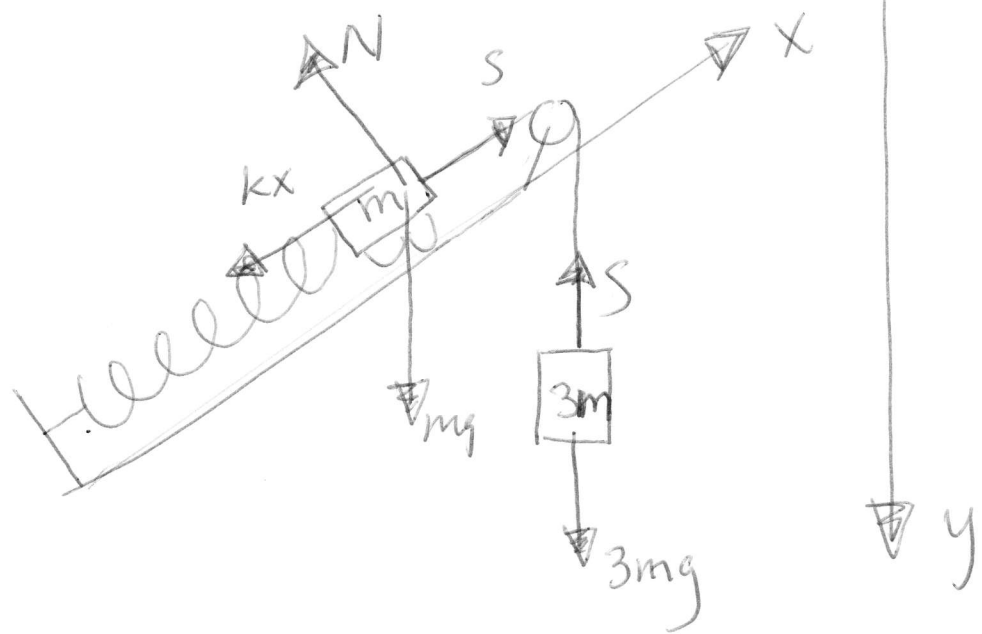
$$(2) \rightarrow S_1 = \frac{mg}{\cos \alpha}$$

Sätt in i (1) och utnyttja övriga samband:

$$-m(a - l \sin \alpha) \omega^2 = -S_2 + mg \tan \alpha \quad \Rightarrow$$

$$S_2 = mg \tan \alpha + m(a - l \sin \alpha) \omega^2$$

3.



$$NII: m\ddot{x} = -kx + S - mg\sin\beta \quad (1)$$

$$3m\ddot{y} = -S + 3mg \quad (2)$$

$$\ddot{x} = \ddot{y} \quad (3)$$

(2) och (3) ger  $S = 3mg - 3m\ddot{x}$   
 insatt i (1) ger

$$m\ddot{x} = -kx + (3mg - 3m\ddot{x}) - mg\sin\beta$$

$$4m\ddot{x} + kx = mg(3 - \sin\beta)$$

$$\ddot{x} + \frac{k}{4m}x = \frac{g}{4}(3 - \sin\beta)$$

$$\omega_n = \sqrt{\frac{k}{4m}} = \frac{1}{2}\sqrt{\frac{k}{m}}$$

$$T_n = \frac{2\pi}{\omega_n} = 4\pi\sqrt{\frac{m}{k}}$$

4.



Minsta värdet för  $\Delta v$  fås då asteroiden tangenterar jorden.

Rörelseimpulsmomentet bevaras:

$$10Rm\Delta v = Rm v_1 \quad (1)$$

Enerin bevaras:

$$\frac{1}{2}m(v_0^2 + \Delta v^2) - \frac{mgR^2}{10R} = \frac{1}{2}m v_1^2 - \frac{mgR^2}{R} \quad (2)$$

(1) ger:  $v_1 = 10\Delta v$ , insatt i (2) ger:

$$\frac{1}{2}(v_0^2 + \Delta v^2) - \frac{gR}{10} = \frac{1}{2}(10\Delta v)^2 - gR \Rightarrow$$

$$100\Delta v^2 - \Delta v^2 = v_0^2 + 2gR - \frac{gR}{5}$$

$$99\Delta v^2 = v_0^2 + \frac{9}{5}gR$$

$$\Delta v^2 = \frac{v_0^2}{99} + \frac{gR}{55}$$

$$\Delta v = \sqrt{\frac{v_0^2}{99} + \frac{gR}{55}}$$

Delta är minsta hastighetsförändringen som krävs för att undvika kollision med jorden