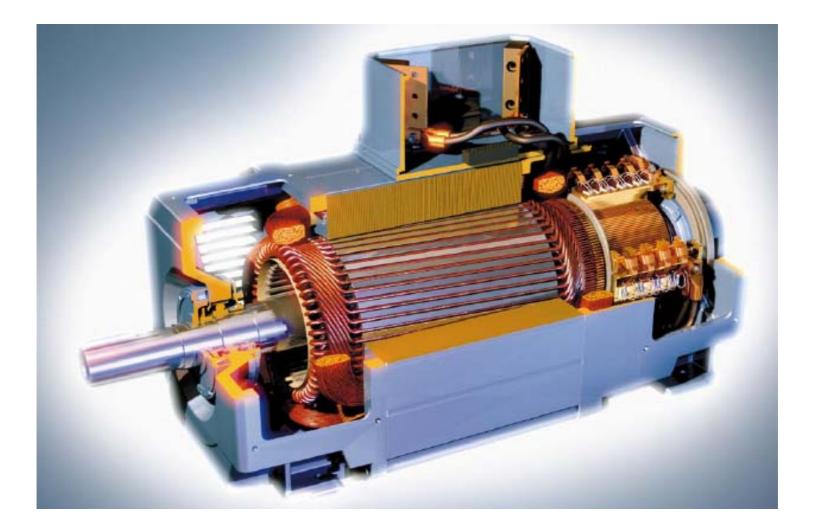
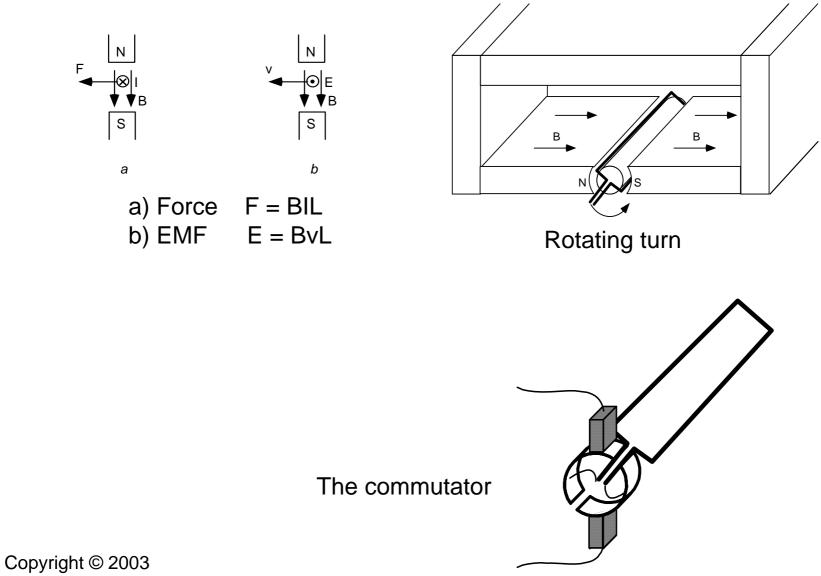
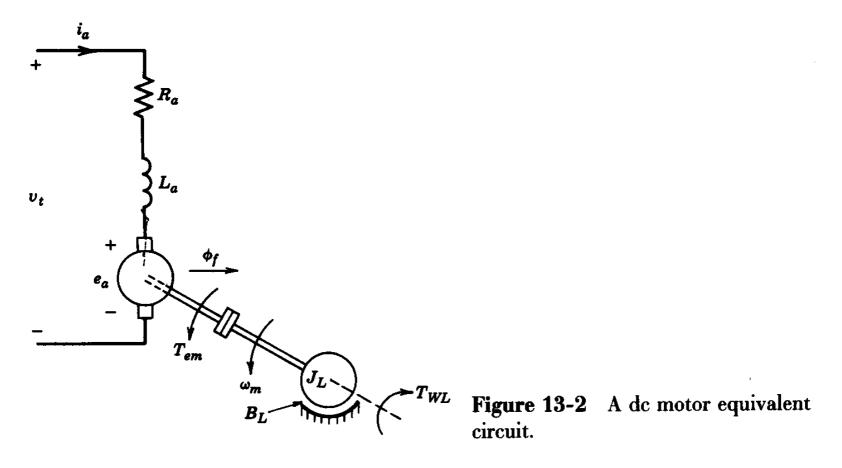
DC motor



A basic dc-machine



DC-Motor Equivalent Circuit



• The mechanical system can also be represented as an electrical circuit

Four-Quadrant Operation of DC-Motor Drives

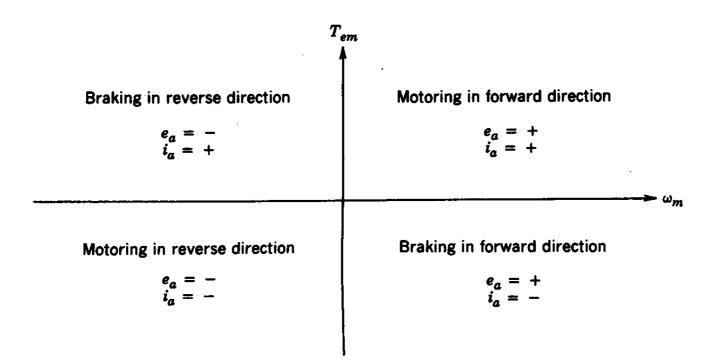


Figure 13-3 Four-quadrant operation of a dc motor.

High performance drives may operate in all four quadrants

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Converter for DC-Motor Drives

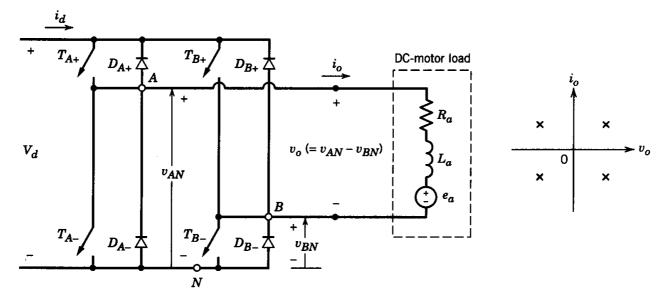
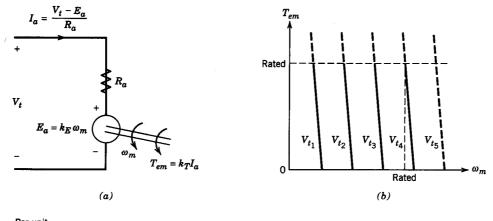


Figure 7-27 Full-bridge dc-dc converter.

• Four quadrant operation is possible

DC-Motor Drive Torque-Speed Characteristics and Capabilities



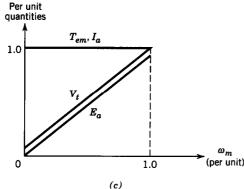
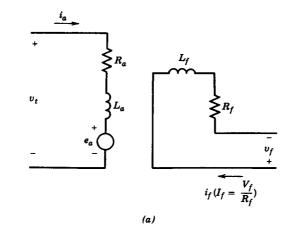
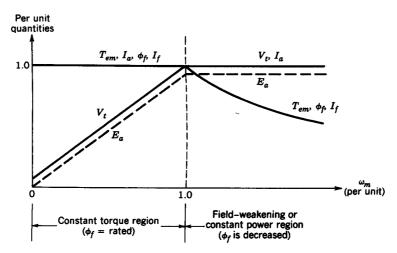


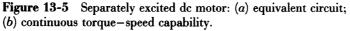
Figure 13-4 Permanent-magnet dc motor: (a) equivalent circuit; (b) torque-speed characteristics: $V_{t5} > V_{t4} > V_{t3} > V_{t2} > V_{t1}$, where V_{t4} is the rated voltage; (c) continuous torque-speed capability.

• With permanent magnets

DC-Motor Drive Capabilities









Controlling Torque, Speed and Position

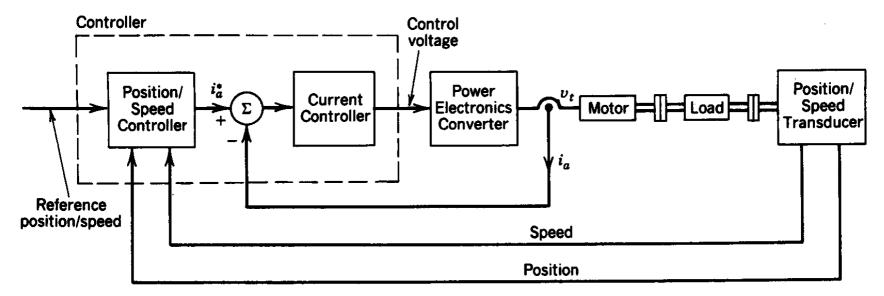


Figure 13-6 Closed-loop position/speed dc servo drive.

Cascaded control is commonly used

Small-Signal Representation of DC Machines

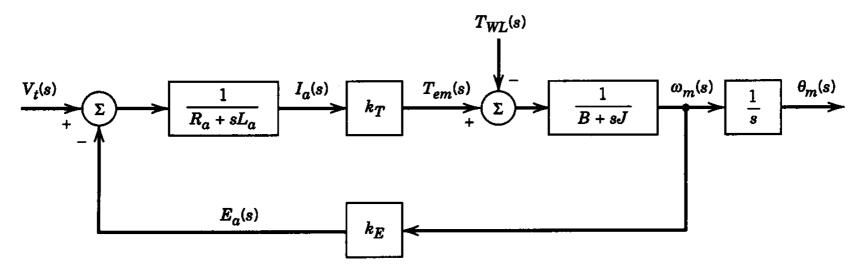


Figure 13-7 Block diagram representation of the motor and load (without any feedback).

Around a steady state operating point

Electrical Time-Constant of the DC Machine

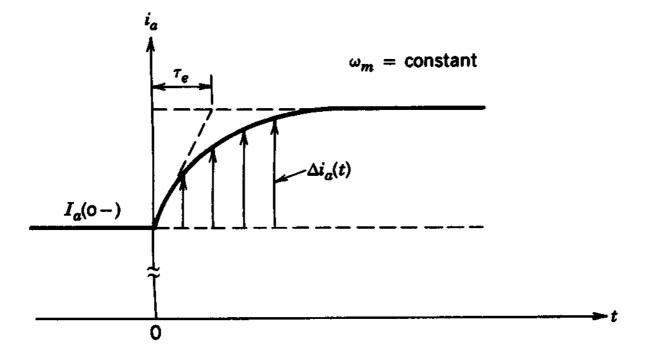
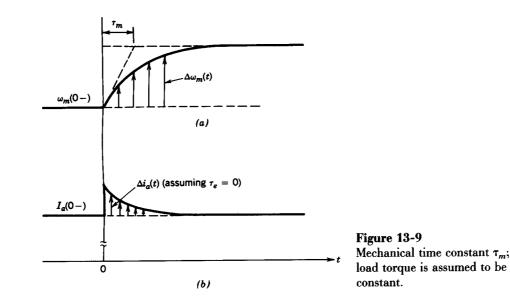


Figure 13-8 Electrical time constant τ_e ; speed ω_m is assumed to be constant.

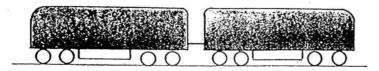
• The speed is assumed constant

Mechanical Time-Constant of the DC Machine

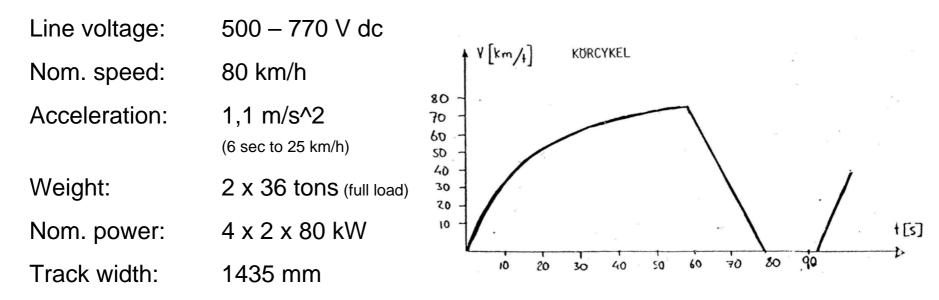


• The load-torque is assumed constant

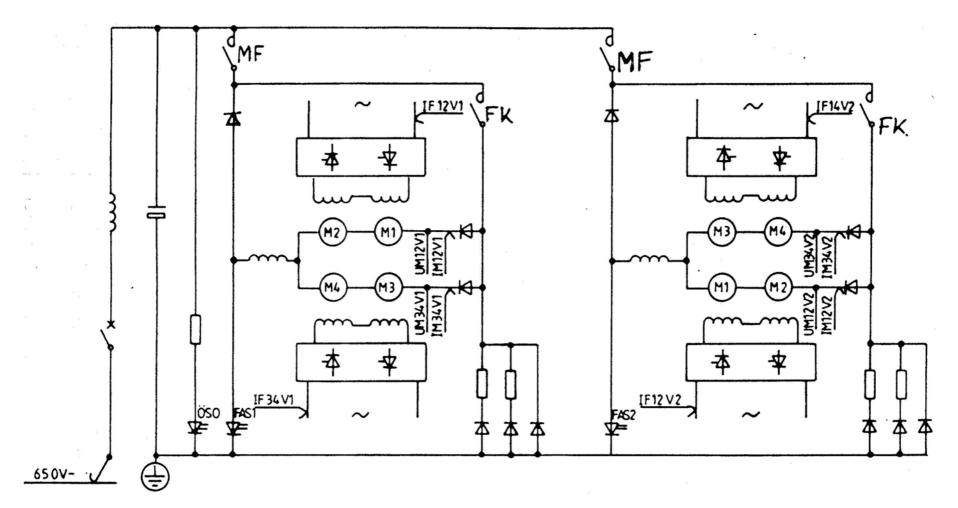
Underground trainset, C15



Main data



Main circuit, C15



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