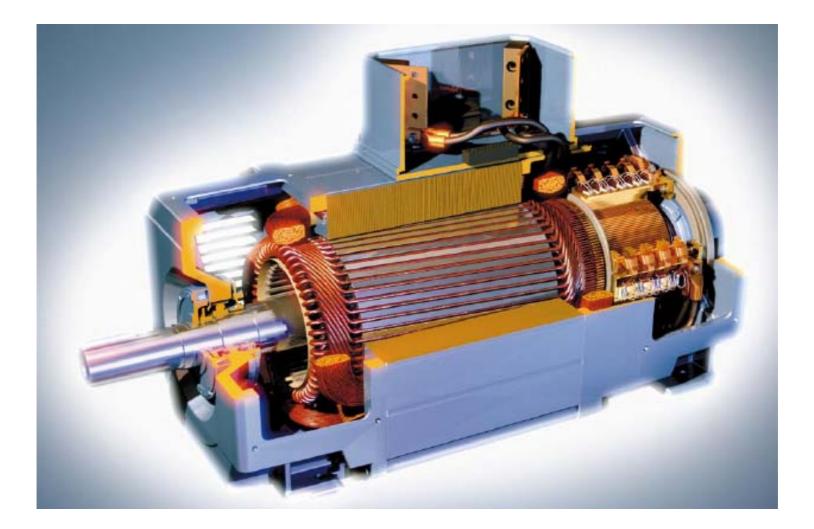
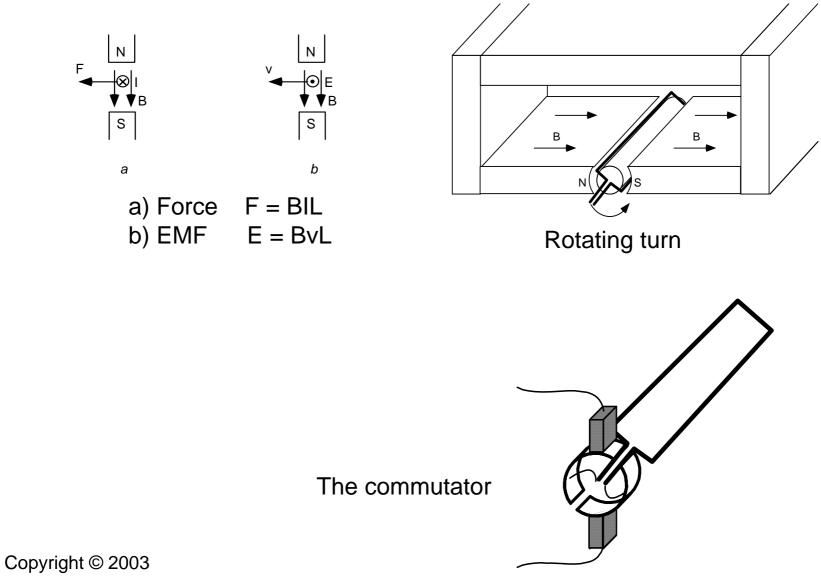
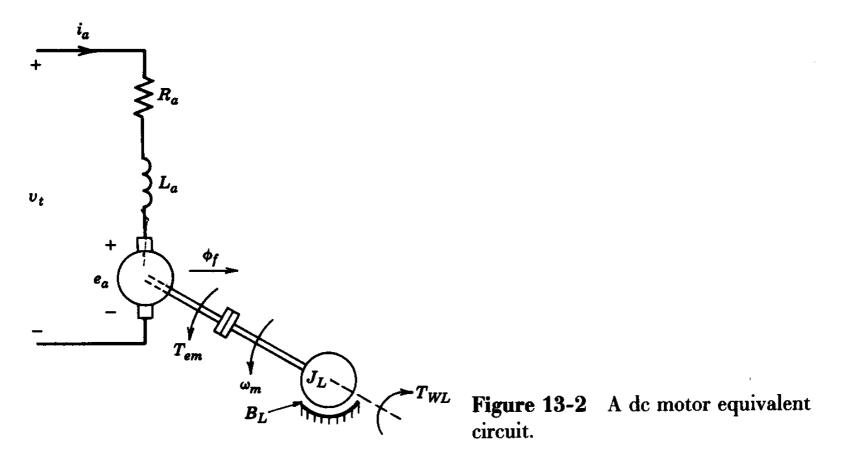
# DC motor



### A basic dc-machine



### **DC-Motor Equivalent Circuit**



• The mechanical system can also be represented as an electrical circuit

### Four-Quadrant Operation of DC-Motor Drives

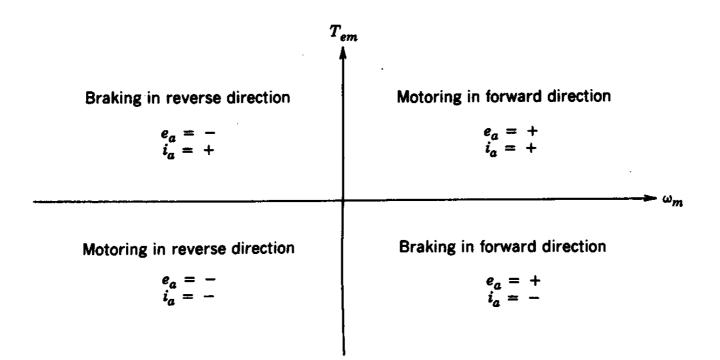


Figure 13-3 Four-quadrant operation of a dc motor.

### High performance drives may operate in all four quadrants

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### **Converter for DC-Motor Drives**

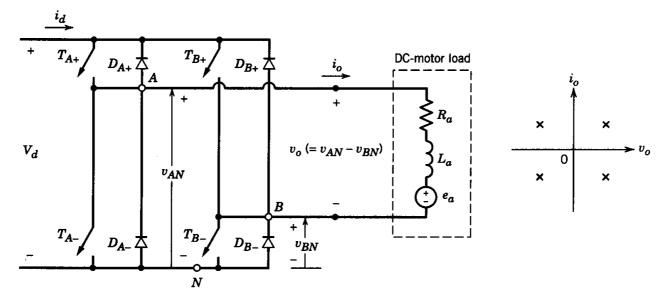
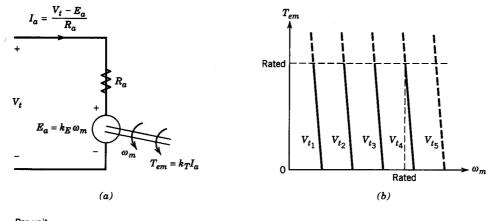
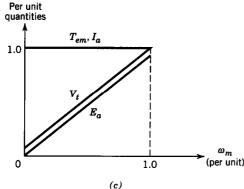


Figure 7-27 Full-bridge dc-dc converter.

• Four quadrant operation is possible

### DC-Motor Drive Torque-Speed Characteristics and Capabilities

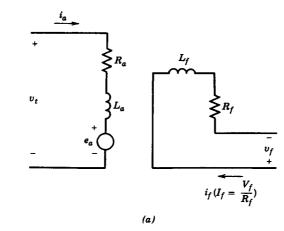


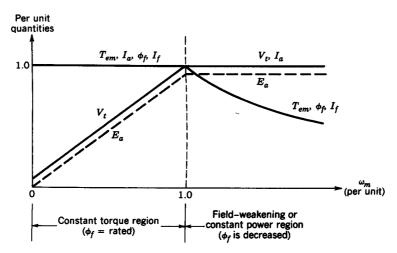


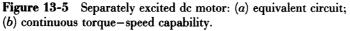
**Figure 13-4** Permanent-magnet dc motor: (a) equivalent circuit; (b) torque-speed characteristics:  $V_{t5} > V_{t4} > V_{t3} > V_{t2} > V_{t1}$ , where  $V_{t4}$  is the rated voltage; (c) continuous torque-speed capability.

• With permanent magnets

### **DC-Motor Drive Capabilities**









## Controlling Torque, Speed and Position

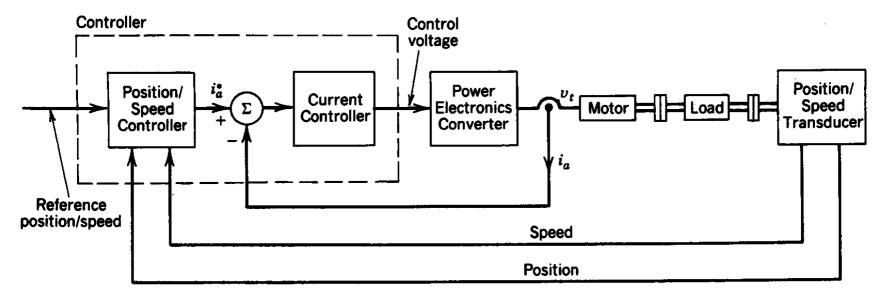


Figure 13-6 Closed-loop position/speed dc servo drive.

### Cascaded control is commonly used

### Small-Signal Representation of DC Machines

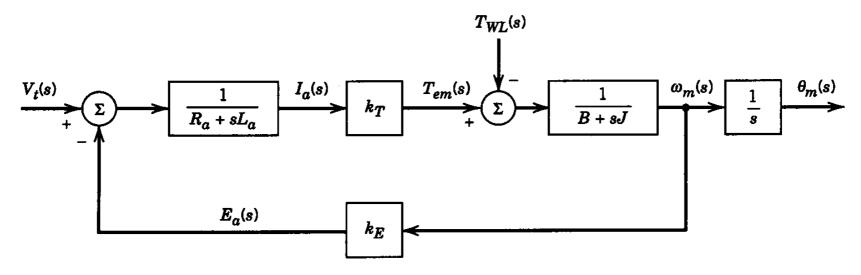
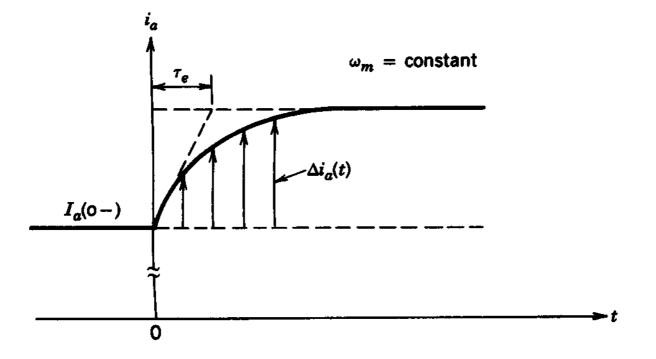


Figure 13-7 Block diagram representation of the motor and load (without any feedback).

#### Around a steady state operating point

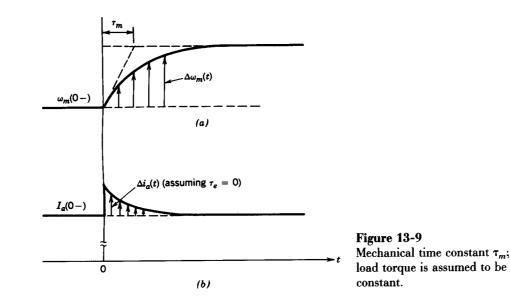
### Electrical Time-Constant of the DC Machine



**Figure 13-8** Electrical time constant  $\tau_e$ ; speed  $\omega_m$  is assumed to be constant.

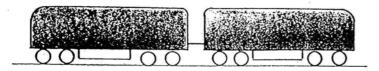
• The speed is assumed constant

### Mechanical Time-Constant of the DC Machine

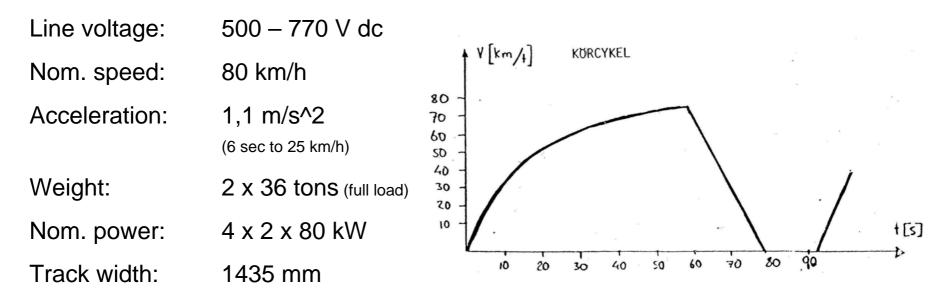


• The load-torque is assumed constant

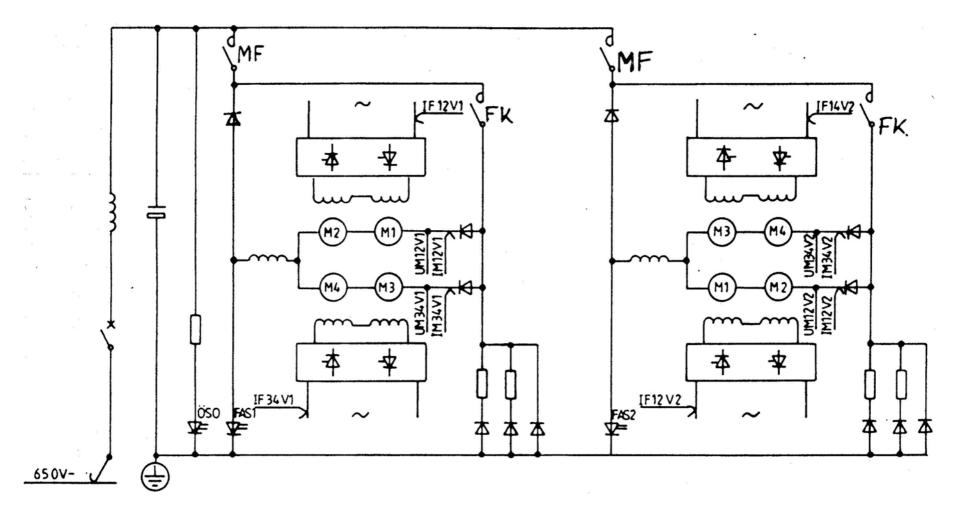
### Underground trainset, C15



#### Main data



### Main circuit, C15



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