

# Lecture Notes

## **Heat Sinks and Component Temperature Control**

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# Need for Component Temperature Control

- All components, capacitors, inductors and transformers, and semiconductor devices and circuits have maximum operating temperatures specified by manufacturer.
- Component reliability decreases with increasing temperature. Semiconductor failure rate doubles for every 10 - 15 °C increase in temperature above 50 °C (approx. rule-of-thumb).
- High component operating temperatures have undesirable effects on components.

## Capacitors

Electrolyte evaporation rate increases significantly with temperature increases and thus shortens lifetime.

## Magnetic Components

- Losses (at constant power input) increase above 100 °C
- Winding insulation (lacquer or varnish) degrades above 100 °C

## Semiconductors

- Unequal power sharing in paralleled or series-connected devices.
- Reduction in breakdown voltage in some devices.
- Increase in leakage currents.
- Increase in switching times.

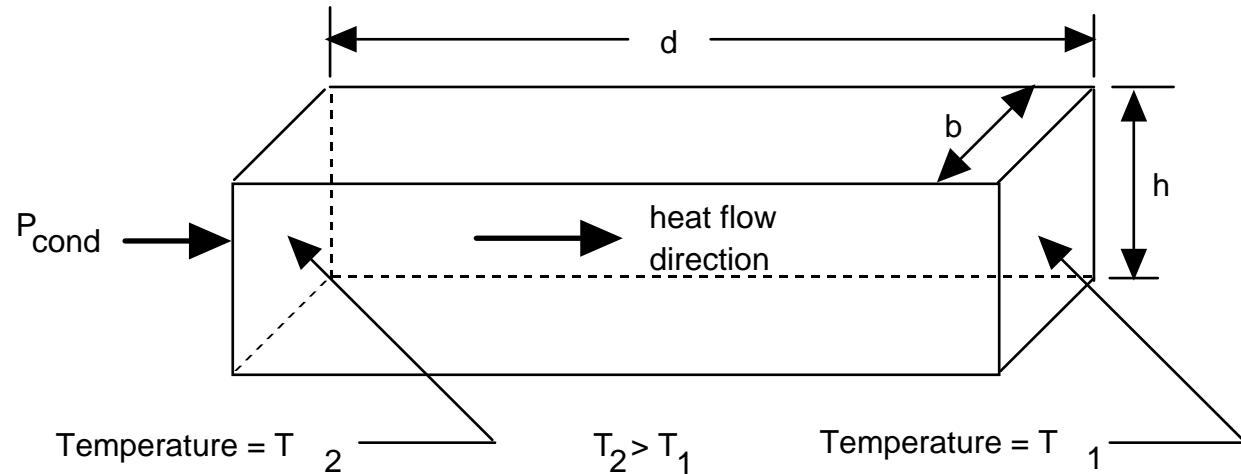
# Temperature Control Methods

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- Control voltages across and current through components via good design practices.
  - Snubbers may be required for semiconductor devices.
  - Free-wheeling diodes may be needed with magnetic components.
- Use components designed to maximize heat transfer via convection and radiation from component to ambient.
  - Short heat flow paths from interior to component surface and large component surface area.
- Component user has responsibility to properly mount temperature-critical components on heat sinks.
  - Apply recommended torque on mounting bolts and nuts and use thermal grease between component and heat sink.
  - Properly design system layout and enclosure for adequate air flow such that heat sinks can operate properly to dissipate heat to the ambient.

# Heat Conduction Thermal Resistance

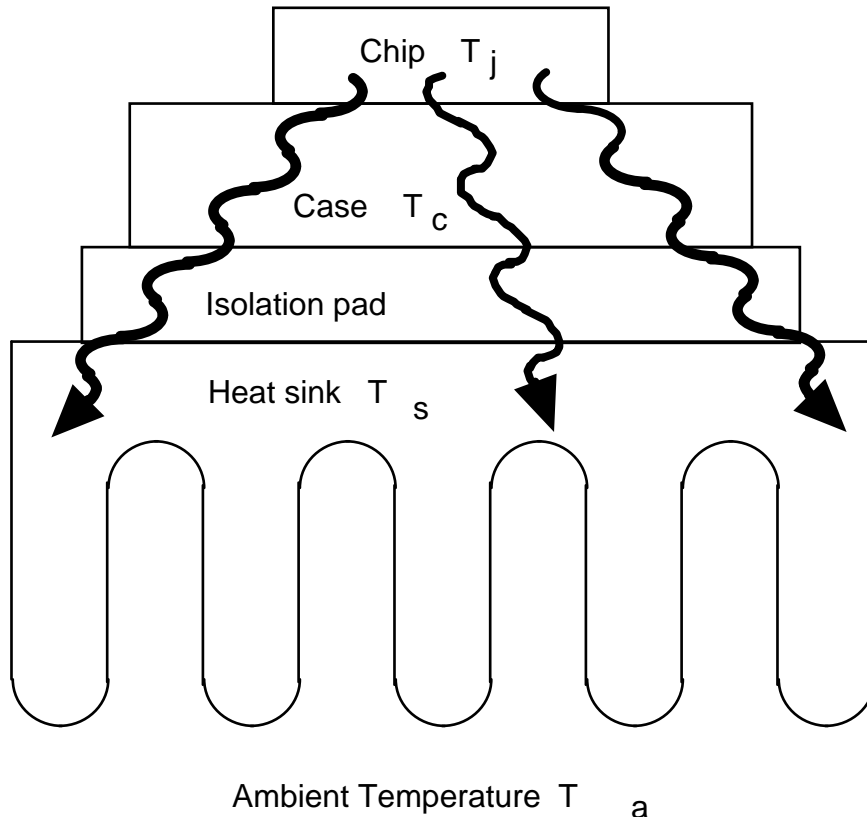
- Generic geometry of heat flow via conduction



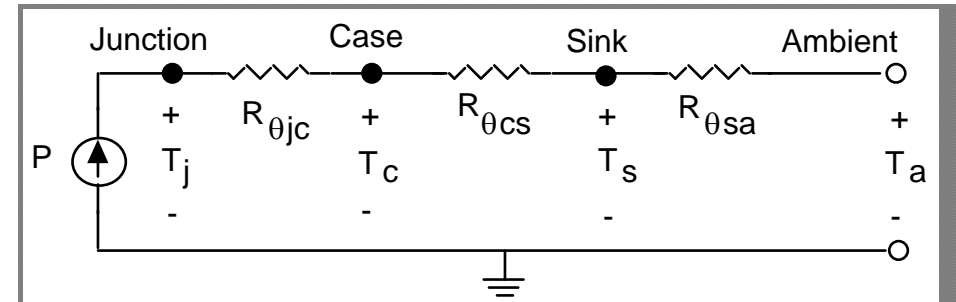
- Heat flow  $P_{\text{cond}} \text{ [W/m}^2\text{]} = \lambda A (T_2 - T_1) / d = (T_2 - T_1) / R_{\theta\text{cond}}$
- Thermal resistance  $R_{\theta\text{cond}} = d / [\lambda A]$ 
  - Cross-sectional area  $A = hb$
  - $\lambda =$  Thermal conductivity has units of  $\text{W}\cdot\text{m}^{-1}\cdot\text{°C}^{-1}$  ( $\lambda_{\text{Al}} = 220 \text{ W}\cdot\text{m}^{-1}\cdot\text{°C}^{-1}$ ).
  - Units of thermal resistance are  $\text{°C/W}$

# Thermal Equivalent Circuits

- Heat flow through a structure composed of layers of different materials.



- Thermal equivalent circuit simplifies calculation of temperatures in various parts of structure.

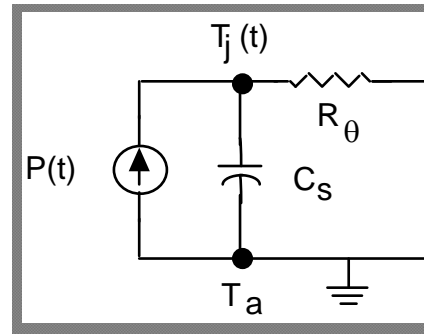


- $T_i = P_d (R_{\theta_{jc}} + R_{\theta_{cs}} + R_{\theta_{sa}}) + T_a$
- If there are parallel heat flow paths, then thermal resistances of the parallel paths combine as do electrical resistors in parallel.

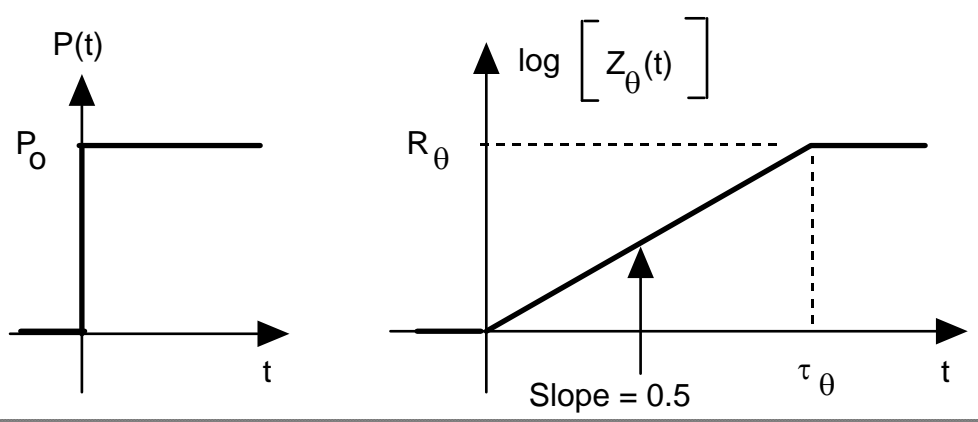
# Transient Thermal Impedance

- Heat capacity per unit volume  $C_v = dQ/dT$  [Joules /°C] prevents short duration high power dissipation surges from raising component temperature beyond operating limits.

- Transient thermal equivalent circuit.  $C_s = C_v V$  where  $V$  is the volume of the component.



- Transient thermal impedance  $Z_\theta(t) = [T_j(t) - T_a]/P(t)$



- $\tau_\theta = \pi R_\theta C_s / 4$  = thermal time constant
- $T_j(t = \tau_\theta) = 0.833 P_o R_\theta$

# Heat Sinks

- Aluminum heat sinks of various shapes and sizes widely available for cooling components.
  - Often anodized with black oxide coating to reduce thermal resistance by up to 25%.
  - Sinks cooled by natural convection have thermal time constants of 4 - 15 minutes.
  - Forced-air cooled sinks have substantially smaller thermal time constants, typically less than one minute.
- Choice of heat sink depends on required thermal resistance,  $R_{\theta sa}$ , which is determined by several factors.
  - Maximum power,  $P_{diss}$ , dissipated in the component mounted on the heat sink.
  - Component's maximum internal temperature,  $T_{j,max}$
  - Component's junction-to-case thermal resistance,  $R_{\theta jc}$ .
  - Maximum ambient temperature,  $T_{a,max}$ .
- $R_{\theta sa} = \{T_{j,max} - T_{a,max}\}P_{diss} - R_{\theta jc}$ 
  - $P_{diss}$  and  $T_{a,max}$  determined by particular application.
  - $T_{j,max}$  and  $R_{\theta jc}$  set by component manufacturer.

# Radiative Thermal Resistance

- Stefan-Boltzmann law describes radiative heat transfer.
  - $P_{\text{rad}} = 5.7 \times 10^{-8} EA [(T_s)^4 - (T_a)^4]$  ;  $[P_{\text{rad}}] = [\text{watts}]$
  - $E = \text{emissivity}$ ; black anodized aluminum  $E = 0.9$  ; polished aluminum  $E = 0.05$
  - $A = \text{surface area [m}^2\text{] through which heat radiation emerges.}$
  - $T_s = \text{surface temperature [}^\circ\text{K] of component. } T_a = \text{ambient temperature [}^\circ\text{K].}$
- $(T_s - T_a)/P_{\text{rad}} = R_{\theta, \text{rad}} = [T_s - T_a][5.7EA \{(T_s/100)^4 - (T_a/100)^4\}]^{-1}$
- Example - black anodized cube of aluminum 10 cm on a side.  $T_s = 120^\circ\text{C}$  and  $T_a = 20^\circ\text{C}$ 
  - $R_{\theta, \text{rad}} = [393 - 293][(5.7)(0.9)(6 \times 10^{-2})\{(393/100)^4 - (293/100)^4\}]^{-1}$
  - $R_{\theta, \text{rad}} = 2.2^\circ\text{C/W}$



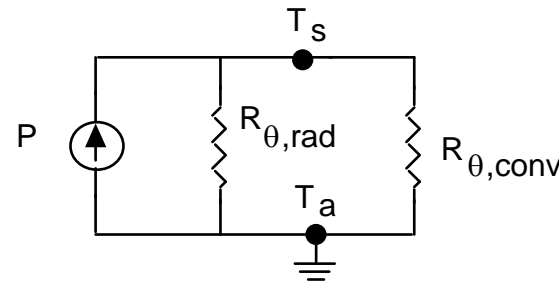
# Convective Thermal Resistance

- $P_{\text{conv}}$  = convective heat loss to surrounding air from a vertical surface at sea level having a height  $d_{\text{vert}}$  [in meters] less than one meter.
  - $P_{\text{conv}} = 1.34 A [T_s - T_a]^{1.25} d_{\text{vert}}^{-0.25}$
  - $A$  = total surface area in  $[m^2]$
  - $T_s$  = surface temperature [ $^{\circ}K$ ] of component.  $T_a$  = ambient temperature [ $^{\circ}K$ ].
- $[T_s - T_a] / P_{\text{conv}} = R_{\theta, \text{conv}} = [T_s - T_a] [d_{\text{vert}}]^{0.25} [1.34 A (T_s - T_a)^{1.25}]^{-1}$ 
  - $R_{\theta, \text{conv}} = [d_{\text{vert}}]^{0.25} \{1.34 A [T_s - T_a]^{0.25}\}^{-1}$
- Example - black anodized cube of aluminum 10 cm on a side.  $T_s = 120^{\circ}C$  and  $T_a = 20^{\circ}C$ .
  - $R_{\theta, \text{conv}} = [10^{-1}]^{0.25} ([1.34] [6 \times 10^{-2}] [120 - 20]^{0.25})^{-1}$
  - $R_{\theta, \text{conv}} = 2.2^{\circ}C/W$

# Combined Effects of Convection and Radiation

- Heat loss via convection and radiation occur in parallel.

- Steady-state thermal equivalent circuit



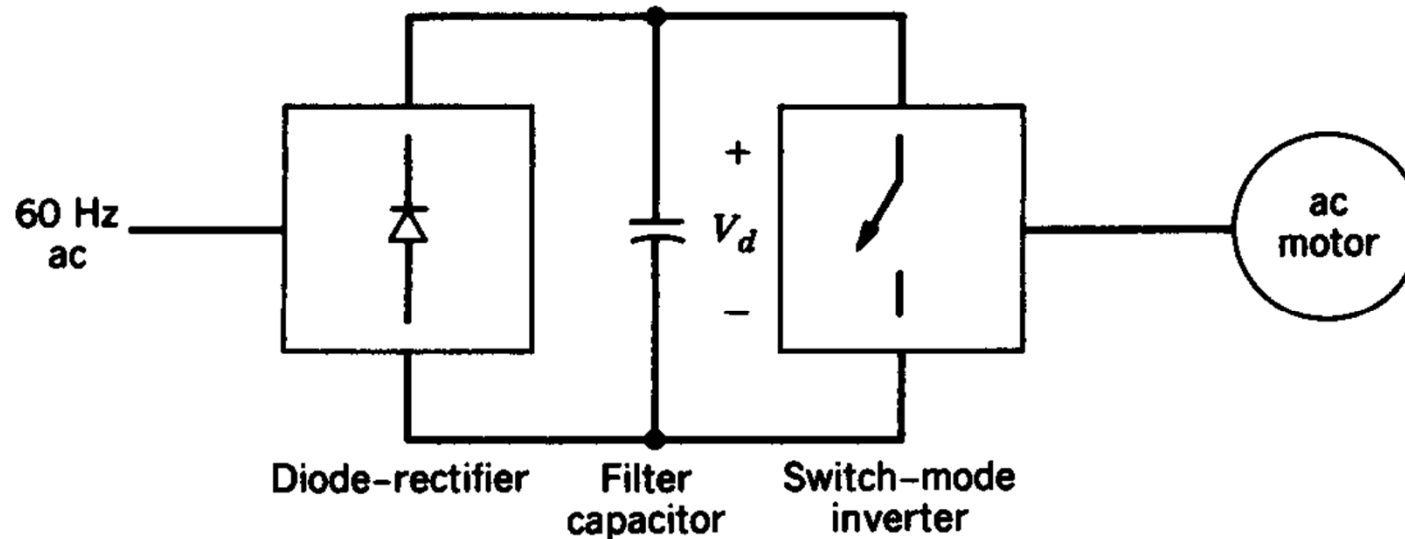
- $R_{\theta,sink} = R_{\theta,rad} R_{\theta,conv} / [R_{\theta,rad} + R_{\theta,conv}]$

- Example - black anodized aluminum cube 10 cm per side

- $R_{\theta,rad} = 2.2 \text{ } ^\circ\text{C/W}$  and  $R_{\theta,conv} = 2.2 \text{ } ^\circ\text{C/W}$

- $R_{\theta,sink} = (2.2) (2.2) / (2.2 + 2.2) = 1.1 \text{ } ^\circ\text{C/W}$

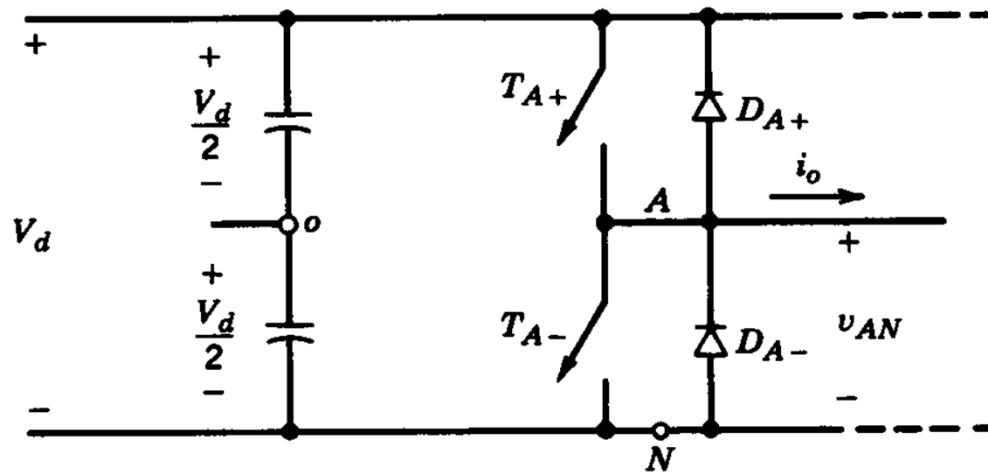
# Switch-Mode DC-AC Inverter



**Figure 8-1** Switch-mode inverter in ac motor drive.

- Block diagram of a motor drive where the power flow is unidirectional

# One Leg of a Switch-Mode DC-AC Inverter



**Figure 8-4** One-leg switch-mode inverter.

- The mid-point shown is fictitious

# Synthesis of a Sinusoidal Output by PWM

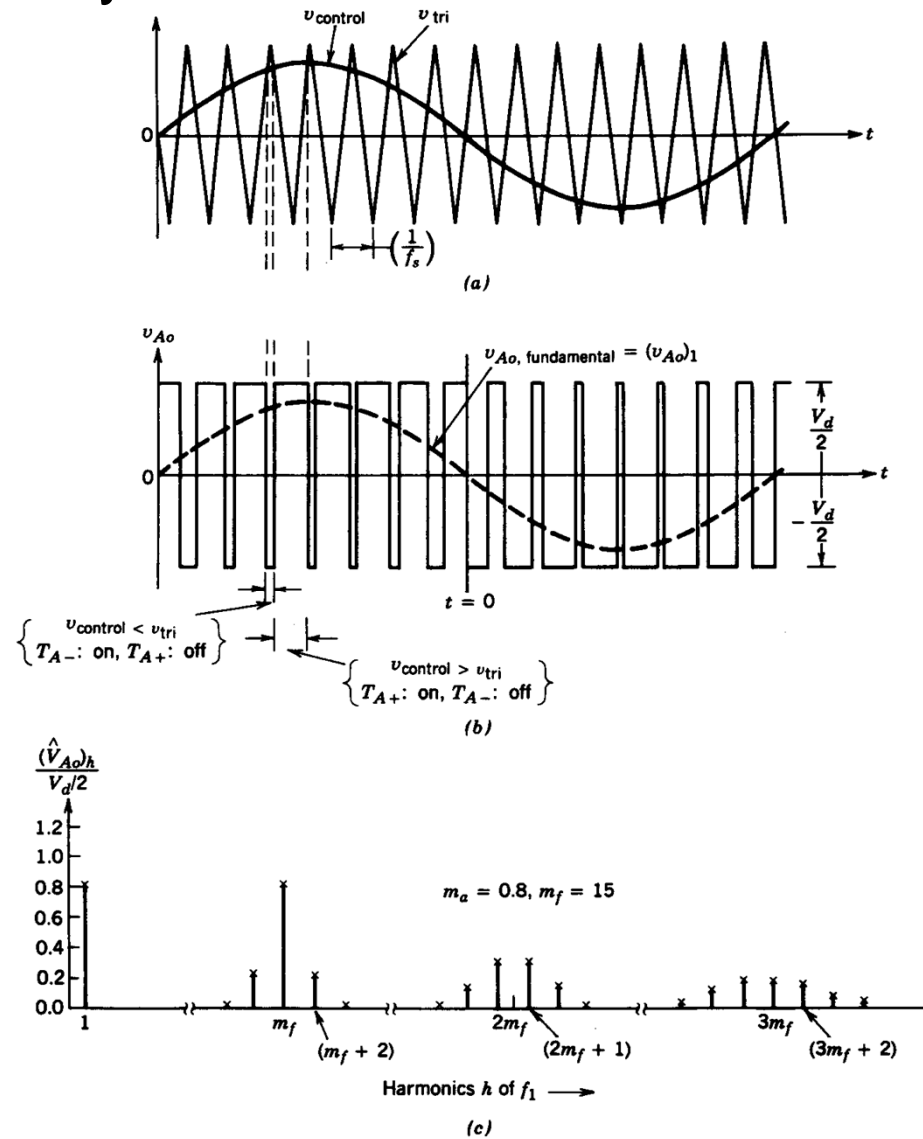
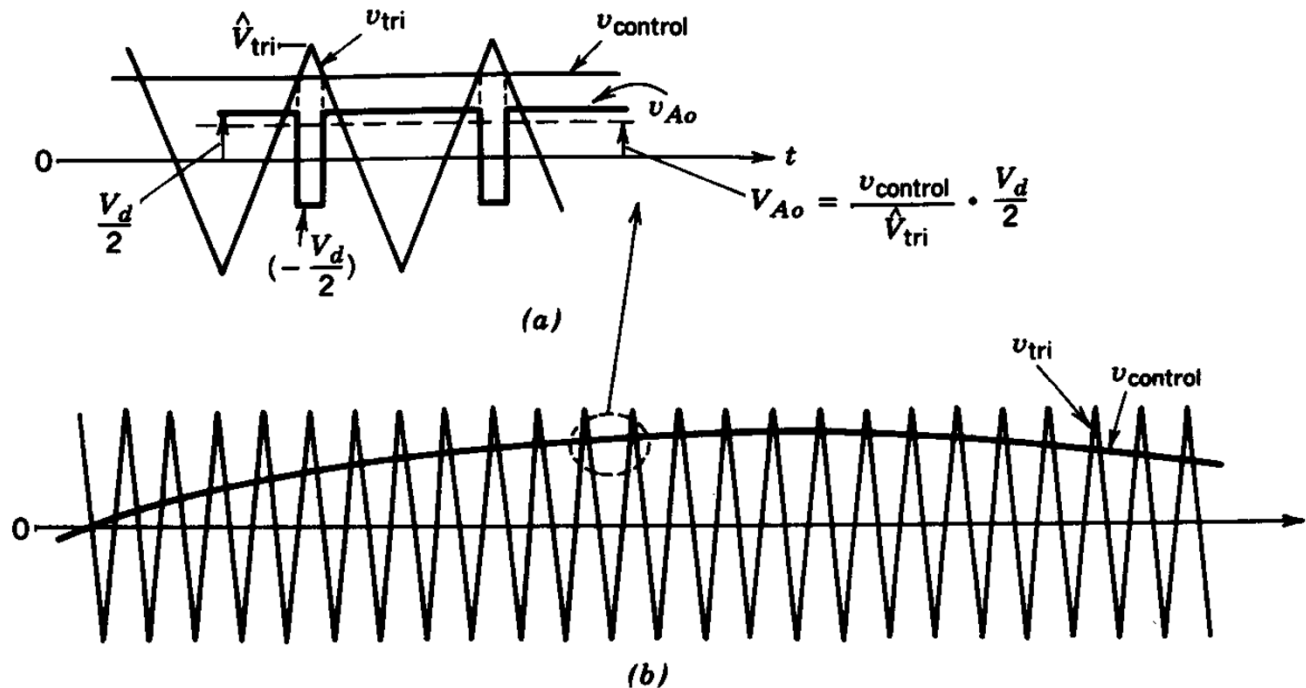


Figure 8-5 Pulse-width modulation.

# Details of a Switching Time Period



**Figure 8-6** Sinusoidal PWM.

- Control voltage can be assumed constant during a switching time-period

# Harmonics in the DC-AC Inverter Output Voltage

**Table 8-1** Generalized Harmonics of  $v_{Ao}$  for a Large  $m_f$ .

$h$ \ $m_a$	0.2	0.4	0.6	0.8	1.0
1	0.2	0.4	0.6	0.8	1.0
<i>Fundamental</i>					
$m_f$	1.242	1.15	1.006	0.818	0.601
$m_f \pm 2$	0.016	0.061	0.131	0.220	0.318
$m_f \pm 4$					0.018
$2m_f \pm 1$	0.190	0.326	0.370	0.314	0.181
$2m_f \pm 3$		0.024	0.071	0.139	0.212
$2m_f \pm 5$				0.013	0.033
$3m_f$	0.335	0.123	0.083	0.171	0.113
$3m_f \pm 2$	0.044	0.139	0.203	0.176	0.062
$3m_f \pm 4$		0.012	0.047	0.104	0.157
$3m_f \pm 6$				0.016	0.044
$4m_f \pm 1$	0.163	0.157	0.008	0.105	0.068
$4m_f \pm 3$	0.012	0.070	0.132	0.115	0.009
$4m_f \pm 5$			0.034	0.084	0.119
$4m_f \pm 7$				0.017	0.050

Note:  $(\hat{V}_{Ao})_h / \frac{1}{2}V_d [= (\hat{V}_{AN})_h / \frac{1}{2}V_d]$  is tabulated as a function of  $m_a$ .

- Harmonics appear around the carrier frequency and its multiples

# Output voltage Fundamental as a Function of the Modulation Index

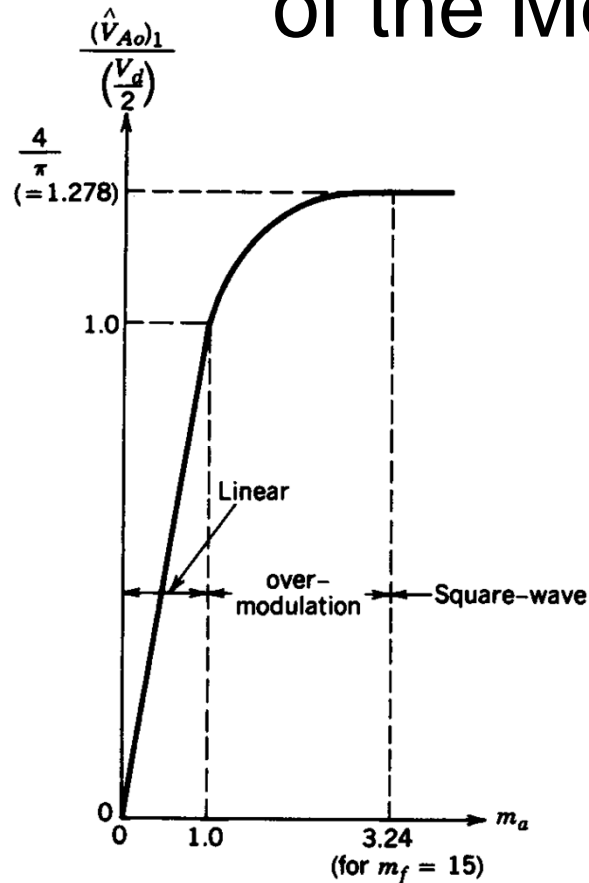


Figure 8-8 Voltage control by varying  $m_a$ .

- Shows the linear and the over-modulation regions; square-wave operation in the limit



# Square-Wave Mode of Operation

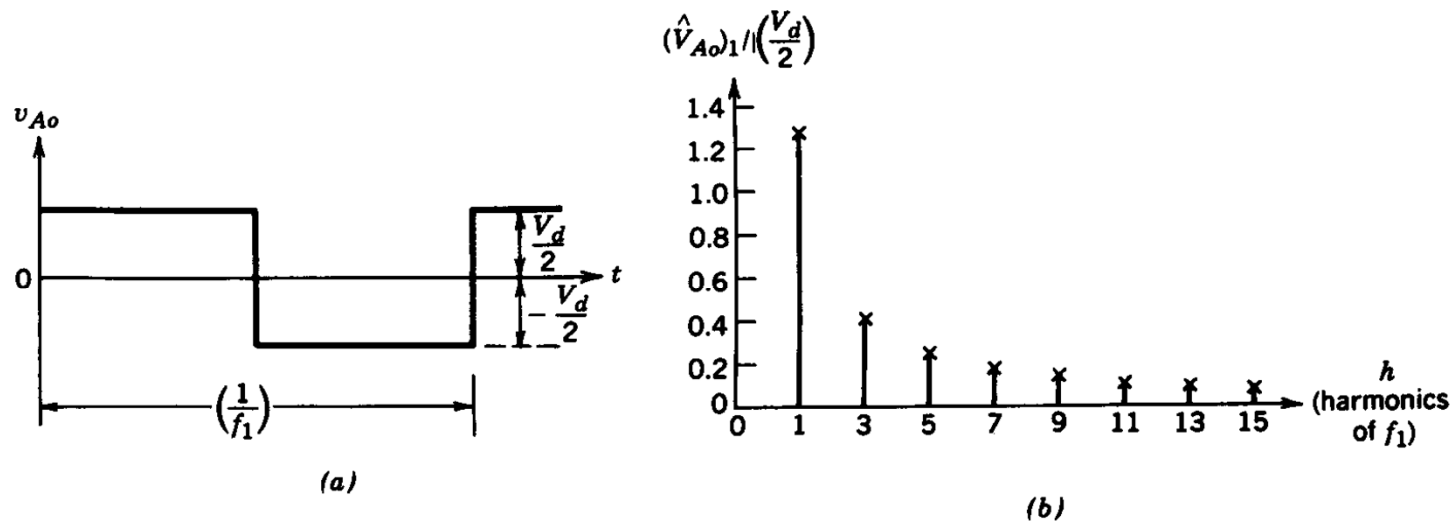


Figure 8-9 Square-wave switching.

- Harmonics are of the fundamental frequency

# Harmonics due to Over-modulation

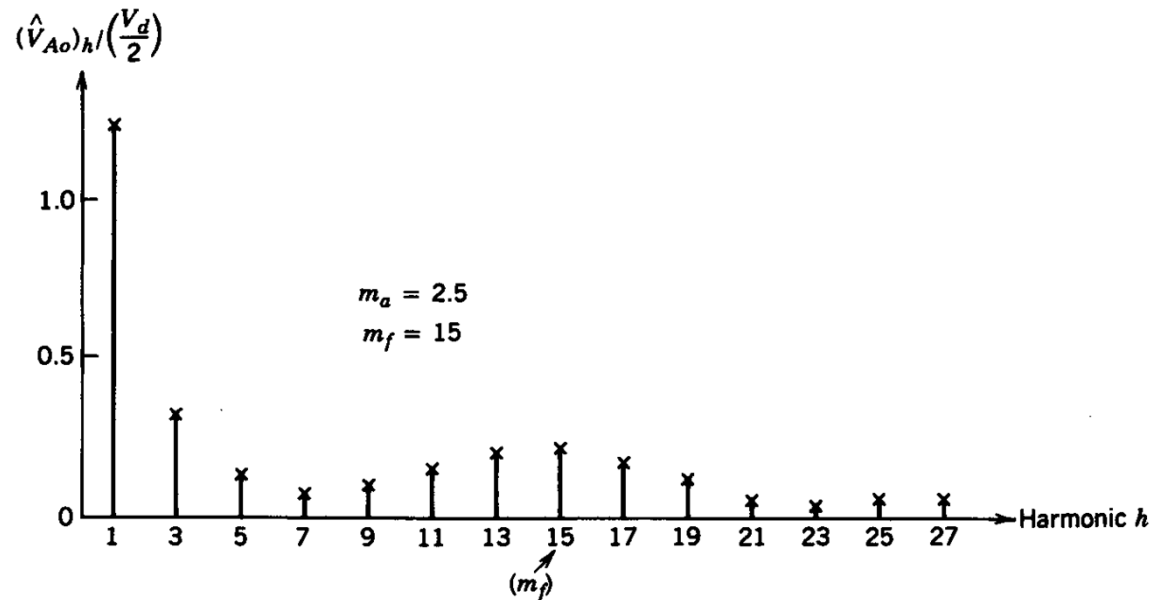


Figure 8-7 Harmonics due to overmodulation; drawn for  $m_a = 2.5$  and  $m_f = 15$ .

- These are harmonics of the fundamental frequency

# Half-Bridge Inverter

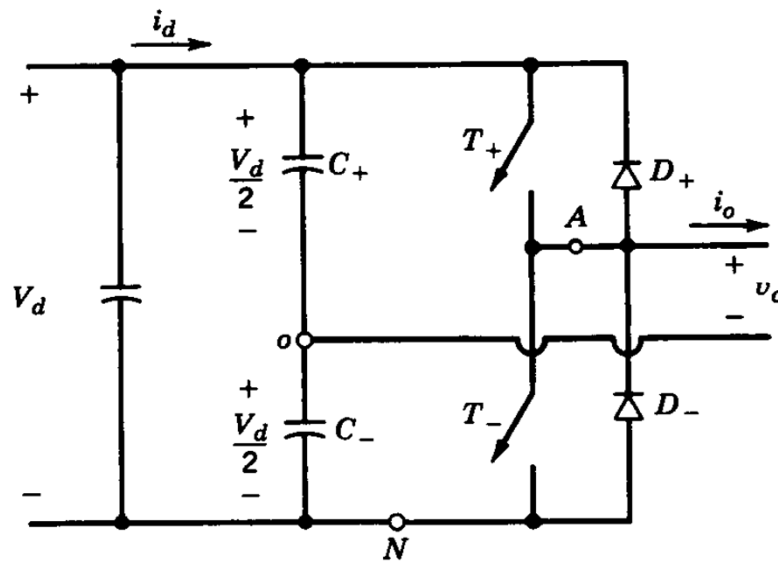
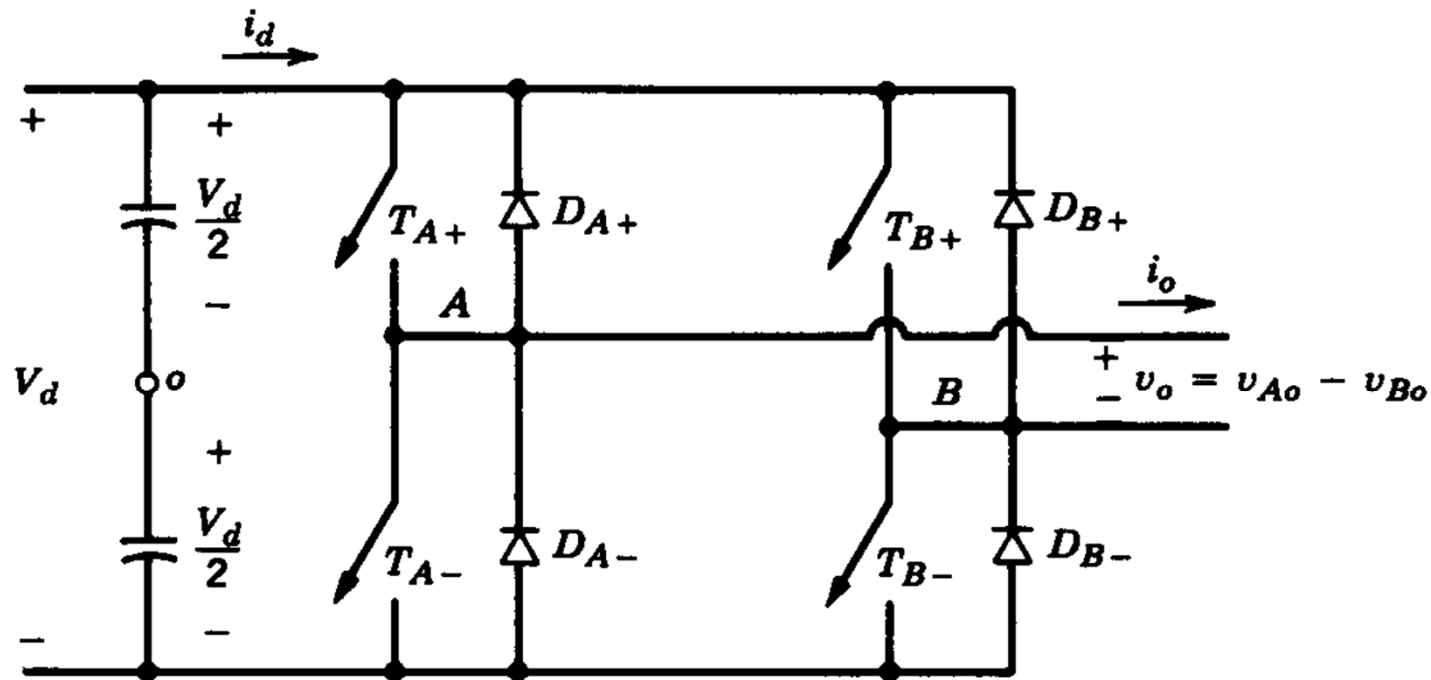


Figure 8-10 Half-bridge inverter.

- Capacitors provide the mid-point

# Single-Phase Full-Bridge DC-AC Inverter



**Figure 8-11** Single-phase full-bridge inverter.

- Consists of two inverter legs

# PWM to Synthesize Sinusoidal Output

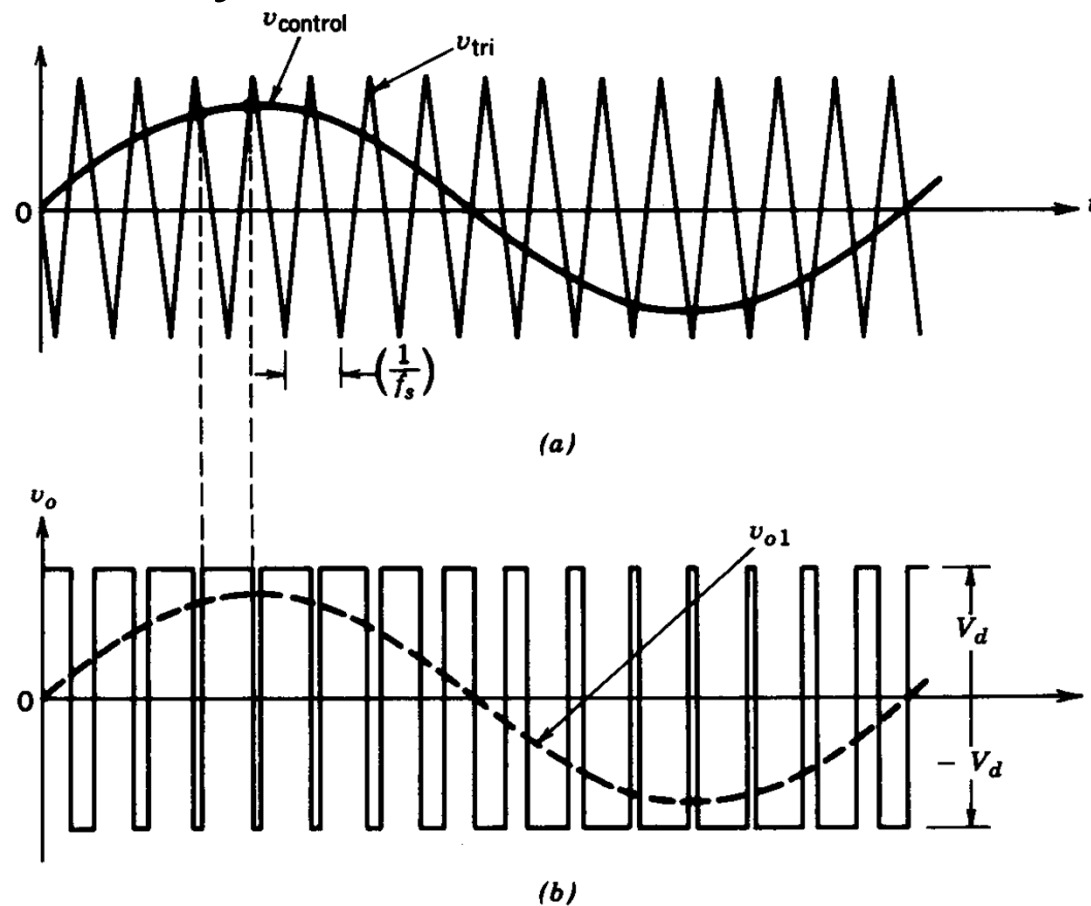


Figure 8-12 PWM with bipolar voltage switching.

- The dotted curve is the desired output; also the fundamental frequency