

CLASSIFICATION OF SYSTEMS

In general: $y(n) = H(u(n))$

Properties: time invariant — time variable

static — dynamic

linear — non-linear

causal — non-causal

stable — unstable



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Common assumption: Linear Time Invariant (LTI)

$$y(n) = \sum_{k=-\infty}^{\infty} h(n-k)u(k) = \sum_{k=-\infty}^{\infty} u(n-k)h(k) = h(n) * u(n)$$

$h(n)$ — the impulse response of the system

Digital Signal Processing

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Before lecture 1

CLASSIFICATION OF SIGNALS

Time-continuous — Time-discrete

Two important classes: \mathcal{L}_1 -signals l_1 -signals

\mathcal{L}_2 -signals l_2 -signals



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Common Properties:

periodic — aperiodic

symmetric — antisymmetric — neither

stochastic — deterministic

Digital Signal Processing

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Before lecture 1

STOCHASTIC SIGNALS

Typical assumption: **(wide sense) stationarity**



Mean value: $E[x(n)] = m_x$, constant, independent on n .

Covariance sequence: $E[x(n)x^*(n-k)] = r_{xx}(k)$ independent of n .

Property: $r_{xx}(-k) = r_{xx}^*(k)$

Average Power: $P_x = E[|x(n)|^2] = r_{xx}(0) \geq 0$

TWO-SIDED Z-TRANSFORM



$$X(z) = Z\{x(k)\} = \sum_{k=-\infty}^{\infty} x(k)z^{-k}$$

Exists only where the series converges.

This region is called the *Region of Convergence* (ROC).

The signal is uniquely determined by the Z-transform **together with** the ROC.

Z-TRANSFORMS, PROPERTIES

Linearity

$$Z\{ax_1(n) + bx_2(n)\} = aZ\{x_1(n)\} + bZ\{x_2(n)\}$$



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Time shift

$$Z\{x(n - k)\} = z^{-k}X(z)$$

Convolution

$$Z\{x_1(n) * x_2(n)\} = Z\{x_1(n)\}Z\{x_2(n)\}$$

Scaling

$$Z\{a^n x(n)\} = X(z/a)$$

Z-TRANSFORMS, MORE PROPERTIES

Time reversal

$$Z\{x(-n)\} = X(z^{-1})$$



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Conjugation (Complex signals)

$$Z\{x^*(n)\} = X^*(z^*)$$

Derivation

$$\frac{dX(z)}{dz} = -z^{-1}Z\{nx(n)\}$$

RATIONAL Z-TRANSFORM

Many systems can be described by a difference equation

$$y(n) = - \sum_{k=1}^{N_a} a_k y(n-k) + \sum_{k=0}^{N_b} b_k x(n-k)$$



Corresponds to a rational Z-transform as transfer function ($a_0 = 1$)

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^{N_b} b_k z^{-k}}{\sum_{k=0}^{N_a} a_k z^{-k}}$$

Zeros: z such that $H(z) = 0$

Poles: z such that $H(z) = \infty$