MULTIRATE SIGNAL PROCESSING

Applications

- · Systems with multiple sampling rates
- Dividing a signal into frequency bands



- Filter design
- Time-frequency analysis
- Used in many audio and video compression schemes

Basic operations

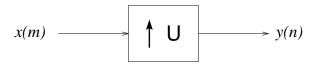
- Downsampling/decimation
- Upsampling/interpolation

Digital Signal Processing

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Lecture 7

Upsampling by a Factor ${\cal U}$





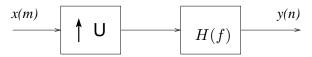
$$\begin{split} y(n) &= \{\dots, x(0), \underbrace{0, \dots, 0}_{U-1 \, \text{zeros}}, x(1), \underbrace{0, \dots, 0}_{U-1 \, \text{zeros}}, x(2), 0, \dots \} \\ &= \begin{cases} x(n/U), & n = 0, \pm U, \pm 2U, \dots \\ 0, & \text{otherwise} \end{cases} \end{split}$$

$$Y(f)=X(fU)$$

$$Y(z) = X(z^U)$$

PROPER INTERPOLATION

Preserve the spectral shape!





$$H(f) = \begin{cases} U, & |f| \le \frac{1}{2U} \\ 0, & \frac{1}{2U} < |f| \le \frac{1}{2} \end{cases}$$

$$Y(f) = \begin{cases} UX(fU), & |f| \le \frac{1}{2U} \\ 0, & \frac{1}{2U} < |f| \le \frac{1}{2} \end{cases}$$

Digital Signal Processing

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Lecture 7

Downsampling by a Factor ${\cal D}$

$$x(m) \longrightarrow \bigvee D \longrightarrow y(n)$$



$$y(n) = \{\dots, x(0), x(D), x(2D), x(3D), \dots\} = x(nD) \quad n = 0, \pm 1, \pm 2, \dots$$

$$Y(f) = \frac{1}{D} \sum_{k=0}^{D-1} X\left(\frac{f-k}{D}\right)$$

$$Y(z) = \frac{1}{D} \sum_{k=0}^{D-1} X\left(z^{1/D} e^{-j2\pi k/D}\right)$$