

19.1

$$G(s) = \frac{3}{s}$$

a) Euler $\Rightarrow H(z) = \frac{3}{\frac{z-1}{zh}} = [h=1s] = \underline{\underline{\frac{3z}{z-1}}}$

b) bilinear $\Rightarrow H(z) = \frac{3}{\frac{2(z-1)}{h(z+1)}} = [h=1s] = \underline{\underline{\frac{3z+3}{2z-2}}}$

19.2

$$G(s) = \frac{1+2s}{1+5s}$$

a) Euler $\Rightarrow H(z) = \frac{1+2 \frac{z-1}{zh}}{1+5 \frac{z-1}{zh}} =$
 $= \frac{zh+2z-2}{zh+5z-5}$ $\left\{ \begin{array}{l} h=1s \Rightarrow H(z) = \frac{3z-2}{6z-5} \\ h=0,1s \Rightarrow H(z) = \frac{2,1z-2}{5,1z-5} \end{array} \right.$

b) bilinear $\Rightarrow H(z) = \frac{1+2 \frac{2(z-1)}{h(z+1)}}{1+5 \frac{2(z-1)}{h(z+1)}} =$
 $= \frac{hz+h+4z-4}{hz+h+10z-10}$ $\left\{ \begin{array}{l} h=1s \Rightarrow H(z) = \frac{5z-3}{11z-9} \\ h=0,1s \Rightarrow H(z) = \frac{4,1z-3,9}{10,1z-9,9} \end{array} \right.$

19.3 $G_R(s) = 4\left(1 + \frac{1}{20s}\right)$

bilinear, $h = 0,5s \Rightarrow$ sätt $s = 4 \frac{z-1}{z+1}$

$$\Rightarrow H(z) = 4 \left(1 + \frac{1}{20 \frac{z-1}{z+1}} \right) = 4 \left(1 + \frac{z+1}{80z-80} \right) =$$

$$= 4 \frac{80z-80+z+1}{80z-80} = 4 \frac{81z-79}{80z-80} = \frac{324z-316}{80z-80}$$

$$\Rightarrow U(z)(80z-80) = E(z)(324z-316)$$

$$U(z)(z-1) = E(z) \left(\frac{324}{80}z - \frac{316}{80} \right)$$

$$\Rightarrow \underline{u(k+1) = u(k) + 4,05e(k+1) - 3,95e(k)}$$

19.4 $G(s) = \frac{1}{1+s} \quad h=1s$

a) Impulsinvariant, $H(z) = z \left(\mathcal{L}^{-1}(G(s)) \right)_{t=kh}$

$$g(t) = e^{-t} \Rightarrow g(kh) = e^{-k} = \left(\frac{1}{e}\right)^k$$

$$\Rightarrow H(z) = \frac{z}{z - \frac{1}{e}} \approx \underline{\underline{\frac{z}{z - 0,37}}}$$

b) Stepinvariant, $H(z) = (1-z^{-1}) Z\left(\mathcal{L}^{-1}\left(\frac{G(s)}{s}\right)_{t=kh}\right)$

$$\frac{G(s)}{s} = \frac{1}{s(s+1)} \Rightarrow \mathcal{L}^{-1}\left(\frac{G(s)}{s}\right) = 1 - e^{-t}$$

$$\Rightarrow \mathcal{L}^{-1}\left(\frac{G(s)}{s}\right)_{t=kh} = 1 - e^{-k}$$

$$\Rightarrow Z\left(\mathcal{L}^{-1}\left(\frac{G(s)}{s}\right)_{t=kh}\right) = \frac{z}{z-1} - \frac{z}{z-\frac{1}{e}}$$

$$\begin{aligned} \Rightarrow H(z) &= \frac{z-1}{z-1} - \frac{z-1}{z-\frac{1}{e}} = 1 - \frac{z-1}{z-\frac{1}{e}} = \\ &= \frac{z-\frac{1}{e}-z+1}{z-\frac{1}{e}} = \frac{1-\frac{1}{e}}{z-\frac{1}{e}} \approx \frac{0,63}{z-0,37} \end{aligned}$$

c) Rampinvariant, $H(z) = \frac{(z-1)^2}{h^2 z} Z\left(\mathcal{L}^{-1}\left(\frac{G(s)}{s^2}\right)_{t=kh}\right)$

$$\frac{G(s)}{s^2} = \frac{1}{s^2(1+s)} = \frac{As+B}{s^2} + \frac{C}{1+s} =$$

$$\left[\frac{As^2 + Bs + As + B + Cs^2}{s^2(1+s)} = \frac{s^2(A+C) + s(A+B) + B}{s^2(1+s)} \right]$$

$$\Rightarrow \begin{cases} B=1 \\ A+B=0; A=-1 \\ A+C=0; C=1 \end{cases} = \frac{-s+1}{s^2} + \frac{1}{1+s} = -\frac{1}{s} + \frac{1}{s^2} + \frac{1}{1+s}$$

$$\Rightarrow \mathcal{L}^{-1}\left(\frac{G(s)}{s^2}\right) = -1 + t + e^{-t}$$

$$\Rightarrow \mathcal{L}^{-1}\left(\frac{G(s)}{s^2}\right)_{t=kh} = -1 + k + e^{-k}$$

$$\Rightarrow Z\left(\mathcal{L}^{-1}\left(\frac{G(s)}{s^2}\right)_{t=kh}\right) = -\frac{z}{z-1} + \frac{z}{(z-1)^2} + \frac{z}{z-\frac{1}{e}}$$

$$\begin{aligned}
\Rightarrow H(z) &= \frac{(z-1)^2}{z} \left(-\frac{z}{z-1} + \frac{z}{(z-1)^2} + \frac{z}{z-\frac{1}{e}} \right) = \\
&= -(z-1) + 1 + \frac{(z-1)^2}{z-\frac{1}{e}} = \\
&= \frac{(1-z)(z-\frac{1}{e}) + z - \frac{1}{e} + z^2 - 2z + 1}{z-\frac{1}{e}} = \\
&= \frac{\cancel{z} - \cancel{z^2} - \frac{1}{e} + z\frac{1}{e} + \cancel{z} - \frac{1}{e} + \cancel{z^2} - \cancel{2z} + 1}{z-\frac{1}{e}} = \\
&= \frac{z\frac{1}{e} + 1 - \frac{2}{e}}{z-\frac{1}{e}} \approx \frac{0,37z + 0,26}{z - 0,37}
\end{aligned}$$

d) bilinear $\Rightarrow H(z) = G(s)_{s=\frac{z-1}{z+1}}$

$$\Rightarrow H(z) = \frac{1}{1 + 2\frac{z-1}{z+1}} = \frac{z+1}{z+1+2z-2} = \frac{z+1}{3z-1}$$

e) $K_{LF} = H(1)$

Impulsinvariant: $K_{LF} \approx \frac{1}{1-0,37} \approx 1,6$

Steginvariant: $K_{LF} \approx \frac{0,63}{1-0,37} = 1,0$

Rampinvariant: $K_{LF} \approx \frac{0,37+0,26}{1-0,37} = 1,0$

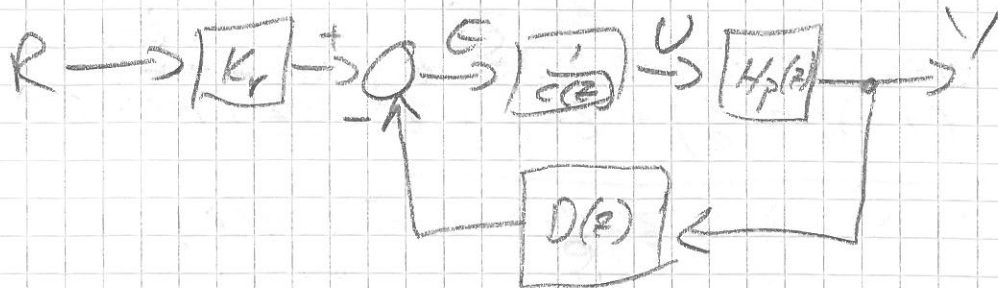
Bilinear: $K_{LF} = \frac{1+1}{3-1} = 1,0$

Impulsinvariant ger en delig approx. av K_{LF}

19.5

$$H_p(z) = \frac{0,65z^{-1} + 0,35z^{-2}}{1 - 0,75z^{-1}} = \frac{B(z)}{A(z)}$$

H_{tot} ska ha dubbelpol, $z=0,5$



$$H_{tot} = K_r \frac{\frac{B}{AC}}{1 + \frac{BD}{AC}} = \frac{B}{AC + BD}$$

Dubbelpol, $z=0,5 \Rightarrow AC + BD = (0,5z^{-1} - 1)^2$

$$(1 - 0,75z^{-1})(1 + C_1 z^{-1}) + (0,65z^{-1} + 0,35z^{-2})(d_0) =$$

$$1 + C_1 z^{-1} - 0,75z^{-1} - 0,75C_1 z^{-2} + 0,65d_0 z^{-1} + 0,35d_0 z^{-2} =$$

$$= 0,25z^{-2}z^{-1} + 1 \Rightarrow \begin{cases} -0,75C_1 + 0,35d_0 = 0,25 & (1) \\ C_1 - 0,75 + 0,65d_0 = -1 & (2) \\ 1 = 1 \end{cases}$$

$$(1) \Rightarrow 0,35d_0 = 0,25 + 0,75C_1; d_0 = \frac{0,25}{0,35} + \frac{0,75}{0,35}C_1 \quad (1')$$

$$(1') \text{ i } (2) \Rightarrow C_1 - 0,75 + \frac{0,65 \cdot 0,25}{0,35} + \frac{0,65 \cdot 0,75}{0,35}C_1 = -1$$

$$C_1 \left(1 + \frac{0,65 \cdot 0,75}{0,35} \right) = -1 + 0,75 - \frac{0,65 \cdot 0,25}{0,35}; C_1 \approx 0,2985 \quad (3)$$

$$(3) \text{ i } (1') \Rightarrow d_0 = \frac{0,25}{0,35} + \frac{0,75}{0,35} \cdot 0,2985 \approx 0,0746$$

$$\Rightarrow \underline{\underline{C(z) = 1 - 0,30z^{-1}}}, \underline{\underline{D(z) = 0,075}}$$

$$K_r = \frac{P(1)}{B(1)} = \frac{(0,5-1)^2}{0,65+0,35} = \underline{\underline{0,25}}$$

$$b) E = RK_r - YD, \quad U = \frac{E}{C}$$

$$E = 0,25R - 0,075Y, \quad U = \frac{Ez}{z-0,30}$$

$$\begin{cases} e(k) = 0,25r(k) - 0,075y(k) \\ u(k+1) = 0,30u(k) + e(k+1) \end{cases}$$

(19.6) a) $y(k) = 0,6y(k-1) + 0,3u(k-1) + 0,7u(k-2)$

$$H_p(z) = \frac{0,3z + 0,7}{z^2 - 0,6z} = \frac{0,3z^{-1} + 0,7z^{-2}}{1 - 0,6z^{-1}}$$

dupbel pol; $z=0,3 \Rightarrow z-0,3=0; z=0,3; z^{-1} = \frac{1}{0,3}$

$$0,3z^{-1} = 1 \Rightarrow P(z) = (0,3z^{-1} - 1)^2$$

$$A(C+BD) = P \text{ (se 19.5)} \Rightarrow$$

$$(1 - 0,6z^{-1})(1 + C_1z^{-1}) + (0,3z^{-1} + 0,7z^{-2})d_0 = (0,3z^{-1} - 1)^2$$

$$1 - 0,6z^{-1} + C_1z^{-1} - 0,6C_1z^{-2} + 0,3d_0z^{-1} + 0,7d_0z^{-2} = 0,09z^{-2} - 0,6z^{-1} + 1$$

$$\Rightarrow \begin{cases} -0,6 + C_1 + 0,3d_0 = -0,6 \\ -0,67C_1 + 0,7d_0 = 0,09 \end{cases} \Rightarrow \begin{cases} C_1 + 0,3d_0 = 0 \\ -0,67C_1 + 0,7d_0 = 0,09 \end{cases}$$

Matlab $\Rightarrow C_1 \approx -0,030, d_0 \approx 0,10$
(A \setminus Y)

$$K_r = \frac{P(1)}{B(1)} = \frac{(0,3-1)^2}{0,3+0,7} = 0,49$$

$$\Rightarrow \underline{C(z) = 1 - 0,030z^{-1}} \quad \underline{D(z) = 0,10} \quad K_r = 0,49$$

$$\begin{aligned} b) \quad H_p = \frac{B}{A} &\Rightarrow H_{tot} = K_r \frac{\frac{B}{AC}}{1 + \frac{BD}{AC}} = \frac{K_r B}{AC + BD} = \\ &= \frac{0,49(0,3z^{-1} + 0,7z^{-2})}{(1 - 0,6z^{-1})(1 - 0,030z^{-1}) + 0,10(0,3z^{-1} + 0,7z^{-2})} \end{aligned}$$

$$\begin{aligned} \text{Sage} &\Rightarrow H_{tot} = \frac{0,147z + 0,343}{z^2 - 0,6z + 0,088} \\ (\text{expr.simplify_full()}) & \end{aligned}$$

$$(19.7) \quad a) \quad H_p = \frac{B}{A} = \frac{0,7}{z - 0,8} = \frac{0,7z^{-1}}{1 - 0,8z^{-1}}$$

$$\text{antel pder } n_p = n_a + b_b - 1 = 1 + 1 - 1 = 1$$

$$p(z) \text{ f } z=0,3 \Rightarrow z^{-1} = \frac{1}{0,3}; \quad 0,3z^{-1} = 1; \quad P(z) = 0,3z^{-1} - 1$$

$$AC + BD = P \Rightarrow (1 - 0,8z^{-1}) \cdot 1 + 0,7z^{-1} \cdot d_0 = -0,3z^{-1} + 1$$

$$\Rightarrow -0,8 + 0,7d_0 = -0,3; \quad d_0 = \frac{0,3+0,8}{0,7} \approx 0,71$$

$$\Rightarrow \underline{C(z) = 1}, \quad \underline{D(z) = 0,71}$$

$$K_r = \frac{P(1)}{B(1)} = \frac{0,3-1}{0,7} = \underline{\underline{1,0}}$$

b) Integralvekan $\Rightarrow A^* = A(1-z^{-1})$

$$\Rightarrow H_{TOT} = \frac{B}{A^*C + BD} = \frac{B}{AC(1-z^{-1}) + BD}$$

Placera båda polerna i $z=0,3$

$$\Rightarrow P(z) = (1-0,3z^{-1})^2$$

$$n_c = n_b - 1 = 0 \Rightarrow C(z) = 1$$

$$n_d = n_a - 1 = 1 \Rightarrow D(z) = d_0 - d_1 z^{-1}$$

Polplaceringskrav, $A^*C + BD = P$:

$$(1-0,8z^{-1})(1-z^{-1}) + 0,7z^{-1}(d_0 - d_1 z^{-1}) = (1-0,3z^{-1})^2$$

$$1-0,8z^{-1}-z^{-1}+0,8z^{-2} + 0,7d_0z^{-1} - 0,7d_1z^{-2} = 1-0,6z^{-1}+0,09z^{-2}$$

$$\Rightarrow \begin{cases} -0,8-1+0,7d_0 = -0,6 \\ 0,8-0,7d_1 = 0,09 \end{cases} \Rightarrow \begin{cases} d_0 \approx 1,7 \\ d_1 \approx 1,0 \end{cases}$$

$$\Rightarrow C(z) = 1, D(z) = 1,7 - 1,0z^{-1}$$

$$K_r = \frac{P(1)}{B(1)} = \frac{(1-0,3)^2}{0,7} = \underline{\underline{0,7}}$$

19.8

$$y(k+1) = 0,6y(k) + 2u(k)$$

$$\Rightarrow H_p(z) = \frac{z}{z-0,6} = \frac{zz^{-1}}{1-0,6z^{-1}}$$

Input kræst. rel $\Rightarrow$ integr. by

$$\Rightarrow H_p^*(z) = \frac{zz^{-1}}{(1-0,6z^{-1})(1-z^{-1})} = \frac{B(z)}{A^*(z)}$$

$$H_{TOT} = \frac{B}{A^*C+BD}$$

antal
poler, $n_p = n_a^* + n_b - 1 = 2 + 1 - 1 = 2$

både polerna: $z=0,2 \Rightarrow P(z) = (1-0,2z^{-1})^2$

$n_c = n_b - 1 = 1 - 1 = 0 \Rightarrow C(z) = 1$ (eller $1-z^{-1}$ om integr. tas med)

$n_d = n_a^* - 1 = 2 - 1 = 1 \Rightarrow D(z) = d_0 + d_1 z^{-1}$

polplaceringssk: $(1-0,6z^{-1})(1-z^{-1}) + 2z^{-1}(d_0 + d_1 z^{-1}) = (1-0,2z^{-1})^2$
 $1-0,6z^{-1}-z^{-1}+0,6z^{-2} + 2d_0 z^{-1} + 2d_1 z^{-2} = 1-0,4z^{-1} + 0,04z^{-2}$

$$\Rightarrow \begin{cases} -0,6-1+2d_0 = -0,4 \\ 0,6+2d_1 = 0,04 \end{cases} ; \begin{cases} d_0 = 0,6 \\ d_1 = -0,28 \end{cases}$$

$$\Rightarrow C(z) = 1-z^{-1}, D(z) = 0,6-0,28z^{-1}$$

$$|K_r = \frac{P(1)}{B(1)} = \frac{(1-0,2)^2}{2} = \underline{\underline{0,32}}$$

19.9

alla poler: $z=0$, $h=1s$,
inga konst. fel på stegf. s tärn
 $\Rightarrow$ integrering

fördöjning = $1s$

tidskonst: $0,63 \cdot y_{ss} = 0,63 \cdot 3 \approx 1,9$

(S. 111)

$y=1,9 \Rightarrow t \approx 3s$

$1s$ död tid $\Rightarrow$ tidskonst, $T=3-1=2$

$K=y_{ss}=3$

$$\Rightarrow G_p(s) = \frac{K e^{-Ls}}{1+Ts} = \frac{3 e^{-s}}{1+2s}$$

Discretisering enl tabell s 314 (dvs steg-invariant transform)

$$\Rightarrow H(z) = z^{-1} \cdot \frac{3(1-e^{-\frac{1}{2}})}{z-e^{-\frac{1}{2}}} = \frac{3(1-e^{-\frac{1}{2}})z^{-2}}{1-e^{-\frac{1}{2}}z^{-1}}$$

$$H(z) \approx \frac{1,2z^{-2}}{1-0,61z^{-1}}$$

$$\Rightarrow H^*(z) = \frac{1,2z^{-2}}{(1-z^{-1})(1-0,61z^{-1})} = \frac{B(z)}{A^*(z)}$$

antal poler, $n_p = n_a + n_b - 1 = 2 + 2 - 1 = 3$

$$n_c = n_b - 1 = 2 - 1 = 1 \Rightarrow C(z) = (1+c_1 z^{-1})(1-z^{-1})$$

$$n_d = n_a - 1 = 2 - 1 = 1 \Rightarrow D(z) = d_0 + d_1 z^{-1} \quad \text{integr.}$$

$$\text{tre poler (origo)} \Rightarrow P(z) = (1-0 \cdot z^{-1})^3 = 1$$

$$\text{polplaceringsskr: } A^*C + BD = P$$

eftersom
 $A^*C + BD$ har högsta
koeff z^{-3} betyder
egenligen z^3 dvs
tre poler

$$(1-z^{-1})(1-0,61z^{-1})(1+C_1z^{-1}) + 1,2z^{-2}(d_0 + d_1z^{-1}) = 1$$

$$(1-z^{-1}-0,61z^{-1}+0,61z^{-2})(1+C_1z^{-1}) + 1,2d_0z^{-2} + 1,2d_1z^{-3} = 1$$

$$1-z^{-1}-0,61z^{-1}+0,61z^{-2} + C_1z^{-1}-C_1z^{-2}-0,61C_1z^{-2}+0,61C_1z^{-3} + 1,2d_0z^{-2} + 1,2d_1z^{-3} = 1$$

$$\begin{cases} -1 - 0,61 + C_1 = 0 \\ 0,61 - C_1 - 0,61C_1 + 1,2d_0 = 0 \\ 0,61C_1 + 1,2d_1 = 0 \end{cases} \Rightarrow \begin{cases} C_1 = 1,61 \\ -1,61C_1 + 1,2d_0 = -0,61 \\ 0,61C_1 + 1,2d_1 = 0 \end{cases}$$

Matlab A \ B $\Rightarrow C_1 \approx 1,61, d_0 \approx 1,65, d_1 \approx -0,82$

$$\Rightarrow C(z) = (1 + 1,61z^{-1})(1 - z^{-1})$$

$$D(z) = 1,65 - 0,82z^{-1}$$

$$K_r = \frac{P(1)}{B(1)} = \frac{1}{1,2} \approx \underline{\underline{0,83}}$$

19.10 $G_p(s) = \frac{K}{s(s+a)}$

inte integrering
Alla poler i origo
3 poler

a) $G_p(s) = \frac{K}{s(s+a)} = \frac{\frac{K}{a}}{s(1+\frac{1}{a}s)}$

Tabell 5.34 $\Rightarrow H(z) = \frac{B(z)}{A(z)} = \frac{K}{a} \cdot \frac{1}{a} \frac{(e^{-ah} - 1 + ah)z^{-1} + (1 - e^{-ah})(1 + ah)z^{-2}}{1 - (1 + e^{-ah})z^{-1} + e^{-ah}z^{-2}}$

$$\frac{U}{R} = K_r \frac{\frac{1}{C}}{1 + \frac{1}{C} \cdot \frac{B}{A} \cdot D} = \frac{K_r A}{AC + BD} \quad ; \quad U = \frac{K_r A}{AC + BD} R \quad \text{ekv(1)}$$

$$R = \frac{1}{1-z^{-1}} \Rightarrow U = \frac{K_r A}{(AC + BD)(1-z^{-1})}$$

Alla poler i origo $\Rightarrow P(z) \equiv 1$, dvs $AC + BD \equiv 1$

$$\Rightarrow U = \frac{K_r A}{1 - z^{-1}}$$

$u_{\max}$ inträffar vid första samplet. Då är alla z^{-x} -termer $= 0$. Enligt (1) är då $A = 1$

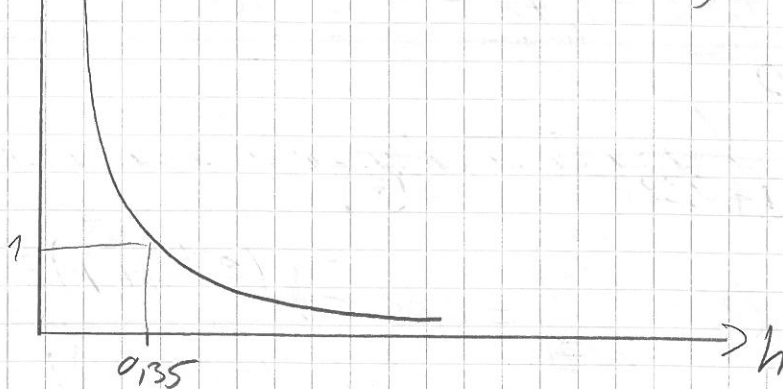
$$K_r = \frac{P(1)}{B(1)} = \frac{1}{\frac{K}{a^2} (e^{-ah} - 1 + ah + 1 - e^{-ah} - ahe^{-ah})}$$

$$= \frac{1}{\frac{K}{a^2} \cdot ah(1 - e^{-ah})} = \frac{1}{\frac{Kh}{a}(1 - e^{-ah})} = \frac{a}{Kh(1 - e^{-ah})}$$

$$\Rightarrow U_{\max} = K_r \Rightarrow U_{\max} = K_r$$

$$U_{\max} = \frac{a}{Kh(1 - e^{-ah})}$$

b) $u_{\max}$



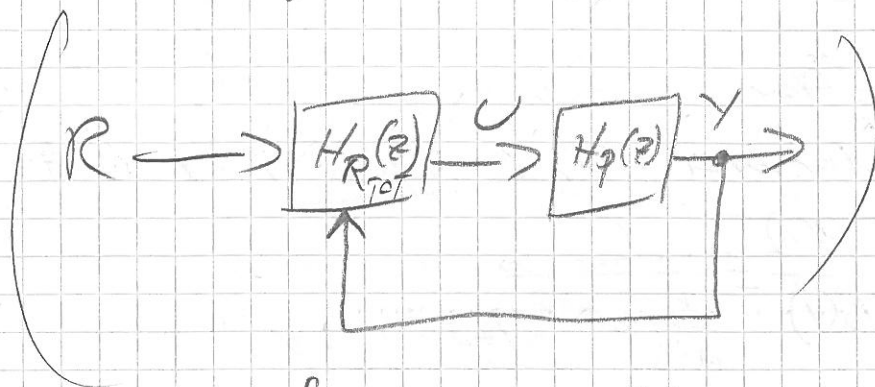
$$a=1, K=10 \Rightarrow u_{\max} = \frac{1}{10h(1 - e^{-h})}$$

(19.11)

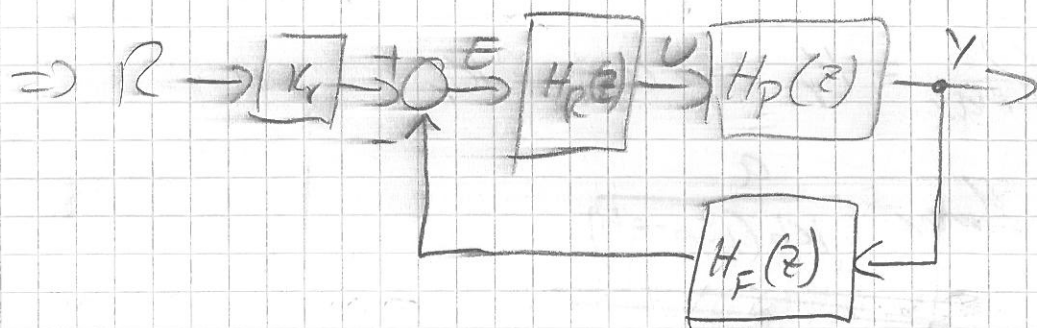
$$G_p(s) = \frac{Y}{U} = \frac{0,05}{s(1+5s)}$$

$$h = 5s$$

U styckvis konst $\Rightarrow$ anv nd steginv. diskretisering



$$H_R(z) = \begin{cases} f(k) = 4,88y(k) - 1,78y(k-1) \\ e(k) = 3,10r(k) - f(k) \\ u(k) = e(k) - 0,32u(k-1) \end{cases}$$



$$H_F(z) = 4,88 - 1,78z^{-1} = D(z)$$

$$K_r = 3,10$$

$$H_R(z) = \frac{1}{1+0,32z^{-1}} = \frac{1}{C(z)}$$

$$\begin{aligned} \text{Tab s. 516} \Rightarrow H_p(z) &= \frac{B(z)}{A(z)} = 0,05 \cdot 5 \cdot \frac{(e^{-1} - 1)z^{-1} + (1 - e^{-1}(1+1))z^{-2}}{1 - (1+e^{-1})z^{-1} + e^{-1}z^{-2}} \\ &\approx \frac{0,092z^{-1} + 0,0661z^{-2}}{1 - 1,3679z^{-1} + 0,3679z^{-2}} \end{aligned}$$

Kar. ekv.: $AC + BD = 0$:

$$\begin{aligned} (1 - 1,3679z^{-1} + 0,3679z^{-2})(1 + 0,32z^{-1}) + \\ + (0,092z^{-1} + 0,0661z^{-2})(4,88 - 1,78z^{-1}) = 0 \end{aligned}$$

$$1 - 0,5989z^{-1} + 0,089z^{-2} + 0,00007z^{-3} = 0$$

stämmer med kar. elev. i facit
Lös. ger alltså två poler i 0,3 och en i origo

$$b) Y = \frac{K_r B}{AC + BD} R \approx$$

$$\approx \frac{3,10(0,092z^{-1} + 0,0661z^{-2})}{1 - 0,5989z^{-1} + 0,089z^{-2} + 0,00007z^{-3}} R \approx$$

$$\approx \frac{0,2852z^{-1} + 0,2049z^{-2}}{\dots} R$$

$$\Rightarrow Y(k) \approx 0,60y(k-1) - 0,090y(k-2) + 0,000070y(k-3) + 0,29r(k-1) + 0,20r(k-2)$$

$$k \rightarrow \infty \Rightarrow y(k) = K_{LF} = H_{TOT}(1) = \frac{3,10,2852 + 0,2049}{1 - 0,5989 + 0,089 + 0,00007} \approx 1,0$$

(19.12) a) $\ddot{\psi} = \frac{1}{J} \cdot M$ Laplace $\Rightarrow s^2 \psi = \frac{1}{J} M$
 $\Rightarrow G(s) = \frac{1}{J s^2} = \frac{1}{1250 s^2}$

b) s. 516 $\Rightarrow H(z) = \frac{5^2}{2 \cdot 1250} \cdot \frac{z^{-1} + z^{-2}}{1 - 2z^{-1} + z^{-2}} =$
 $= 10^{-2} \frac{z^{-1} + z^{-2}}{1 - 2z^{-1} + z^{-2}}$

$$c) H_{TOT}(z) = K_r \frac{B}{A(z)D(z)} \quad \text{All poles } |a| < 1 \Rightarrow P(z) = 1$$

$$n_p = n_a + n_b - 1 = 2 + 2 - 1 = 3$$

$$n_c = n_a - 1 = 2 - 1 = 1 \Rightarrow C(z) = 1 + c_1 z^{-1}$$

$$n_d = n_b - 1 = 2 - 1 = 1 \Rightarrow D(z) = d_0 + d_1 z^{-1}$$

$$\text{polplacement: } (1 - 2z^{-1} + z^{-2}) (1 + c_1 z^{-1}) + 10^{-2} (z^{-1} + z^{-2}) (d_0 + d_1 z^{-1}) = 1$$

$$1 - 2z^{-1} + z^{-2} + c_1 z^{-1} - 2c_1 z^{-2} + c_1 z^{-3} + 10^{-2} d_0 z^{-1} + 10^{-2} d_1 z^{-2} + 10^{-2} d_0 z^{-2} + 10^{-2} d_1 z^{-3} = 1$$

$$\Rightarrow \begin{cases} z^{-1}: -2 + c_1 + 10^{-2} d_0 = 0 & (1) \\ z^{-2}: 1 - 2c_1 + 10^{-2} d_0 + 10^{-2} d_1 = 0 & (2) \\ z^{-3}: c_1 + 10^{-2} d_1 = 0 & (3) \end{cases}$$

$$(1) \Rightarrow d_0 = 10^2 (2 - c_1) \quad (3) \Rightarrow d_1 = -10^2 c_1 \quad (3')$$

$$(1') \& (3') : (2) \Rightarrow 1 - 2c_1 + 10^{-2} \cdot 10^2 (2 - c_1) + 10^{-2} \cdot (-10^2 c_1) = 0$$

$$1 - 2c_1 + 2 - c_1 - c_1 = 0 \Rightarrow -4c_1 = -3 \Rightarrow c_1 = 0,75 \quad (4)$$

$$(4) : (1) \Rightarrow -2 + 0,75 + 10^{-2} d_0 = 0; 10^{-2} d_0 = 1,25; \underline{d_0 = 125}$$

$$(4) : (3) \Rightarrow 0,75 + 10^{-2} d_1 = 0; \underline{d_1 = -75}$$

$$K_r = \frac{P(1)}{B(1)} = \frac{1}{10^{-2}(1+1)} = 10^2 \cdot 0,5 = 50$$

$$\underline{\text{Sver:}} K_r = 50, C(z) = 1 + 0,75z^{-1}, D(z) = 125 - 75z^{-1}$$

$$d) \frac{\psi}{\psi_{ref}} = H_{TOT}(z) = K_r \frac{B}{A(z)D(z)} =$$

$$= 50 \frac{10^{-2} (z^{-1} + z^{-2})}{(1 - 2z^{-1} + z^{-2}) (1 + 0,75z^{-1}) + 10^{-2} (z^{-1} + z^{-2}) (125 - 75z^{-1})} =$$

$$\begin{aligned}
 &= \frac{0,5z^{-1} + 0,5z^{-2}}{1 - 2z^{-1} + z^{-2} + 0,75z^{-1} - 1,5z^{-2} + 0,75z^{-3} + 1,25z^{-1} + 1,25z^{-2} - 0,75z^{-2} - 0,75z^{-3}} \\
 &= \frac{0,5z^{-1} + 0,5z^{-2}}{1 + z^{-1}(-2 + 0,75 + 1,25) + z^{-2}(1 - 1,5 + 1,25 + 0,75) + z^{-3}(0,75 + 0,75)} \\
 &= \frac{0,5z^{-1} + 0,5z^{-2}}{1 \text{ stummer } 0} = 0,5z^{-1} + 0,5z^{-2}
 \end{aligned}$$

$$\Rightarrow \psi = (0,5z^{-1} + 0,5z^{-2}) \psi_{\text{ref}} \Rightarrow \psi(k) = 0,5 \psi_{\text{ref}}(k-1) + 0,5 \psi_{\text{ref}}(k-2)$$

$$\frac{M}{\psi_{\text{ref}}} = K_r \frac{\frac{1}{s}}{1 + \frac{1}{s} \cdot \frac{B}{A} \cdot D} = K_r \frac{A}{AC + BD} = [AC + BD = 1] =$$

$$= K_r A = 50(1 - 2z^{-1} + z^{-2}) = 50 - 100z^{-1} + 50z^{-2}$$

$$\Rightarrow M = (50 - 100z^{-1} + 50z^{-2}) \psi_{\text{ref}}$$

$$\Rightarrow M(k) = 50 \psi_{\text{ref}}(k) - 100 \psi_{\text{ref}}(k-1) + 50 \psi_{\text{ref}}(k-2)$$

c)

k	$\psi_{\text{ref}} [\text{rad}]$	$M [\text{Nm}]$	$\psi [\text{rad}]$
1	0,1745	8,7	0
2	0,1745	-8,7	0,087
3	0,1745	0	0,1745
4	0,1745	0	0,1745
5	0,1745	0	0,1745

formler / sverre

(d) $\Rightarrow$

$$F = ma$$

$$N = \frac{\text{kg} \cdot \text{m}}{\text{s}^2}$$

$$\dot{\psi} = \frac{m}{s}$$

$$\frac{1}{s^2} = \frac{\text{kg} \cdot \text{m}^2}{\text{kg} \cdot \text{s}^2}$$

OK!

19.13

$$G_P = \frac{K_P}{1+as}$$

$$G_R = K_R \left(1 + \frac{1}{Ts}\right) = K_R \frac{1+Ts}{Ts}$$

$$G_{TOT} = \frac{\frac{K_P K_R (1+Ts)}{Ts (1+as)}}{1 + \frac{K_P K_R (1+Ts)}{Ts (1+as)}} = \frac{K_P K_R (1+Ts)}{Ts (1+as) + K_P K_R (1+Ts)} =$$

$$= \frac{K_P K_R (1+Ts)}{Ts + Ts^2 + K_P K_R + K_P K_R Ts} = \frac{K_P K_R + K_P K_R Ts}{K_P K_R + Ts(T + K_P K_R) + Ts^2}$$

dubbelpol: $s = -1 \Rightarrow P(s) = (s+1)^2 = s^2 + 2s + 1$

polplaceringsskr: $K_P K_R + s(T + K_P K_R) + s^2 \cdot aT = s^2 + 2s + 1$

$$\Rightarrow \begin{cases} K_P K_R = 1 \\ T + K_P K_R T = 2 \\ aT = 1 \end{cases} \quad \begin{cases} K_P = 3 \\ a = 2 \end{cases} \Rightarrow \begin{cases} 3K_R = 1 \\ T + 3K_R T = 2 \\ 2T = 1 \end{cases} \quad \text{Svar lösning}$$

Sätt $P'(s) = 3P(s) \Rightarrow$
 (För att $K_P K_R$ ska bli 1)
 vilket eliminerar en
 av de tre ekv.
 $\begin{cases} 3K_R = 3 & (1) \\ T + 3K_R T = 6 & (2) \\ 2T = 3 & (3) \end{cases}$

(1) $\Rightarrow K_R = 1$ (1') (3) $\Rightarrow T = 1,5$ (3')

(1') & (3') i (2) $\Rightarrow 1,5 + 3 \cdot 1 \cdot 1,5 = 6$ OK!

Svar: $G_R = 1 + \frac{1}{1,5s} \Rightarrow G_{TOT} = \frac{3(3 + 4,5s)}{3 + 6s + 3s^2}$

(9.14)

- a) För att utvärderet ska vara lika med referensvärdet
- b) Den ger snabbast möjliga insvagningsförlopp.
+ : snabb , - : stora styrsignaler
- c) ^{ss-} Felet vid stegformade störningar elimineras
- d) + : Ofta bättre egenskaper, speciellt vid svårreglerade processer, som tex säckarna med lång död tid.
Enkel att kombinera med parametridentificering, vilken ger systemets diskreta övertillfunkt.
Lämpar sig väl för datorstödd reglering
- : Svårt bestämma polernas placering
Svårt få tag i enkelsregulatorer

(9.15)

- a) Olika regulatorer används för olika reglerområden. Reglerområdet väljs mha en styrande parameter
- b) Uppskattn. av $H_p(z)$ beräknas en efter varje sampel. Utskän $H_p(z)$ beräknas även $H_p(z)$ efter varje sampel
- c) + : Styrande parameter ej nödvändig för beräkningar
- : Långsam