

# Introduction to Agent and Multiagent Systems



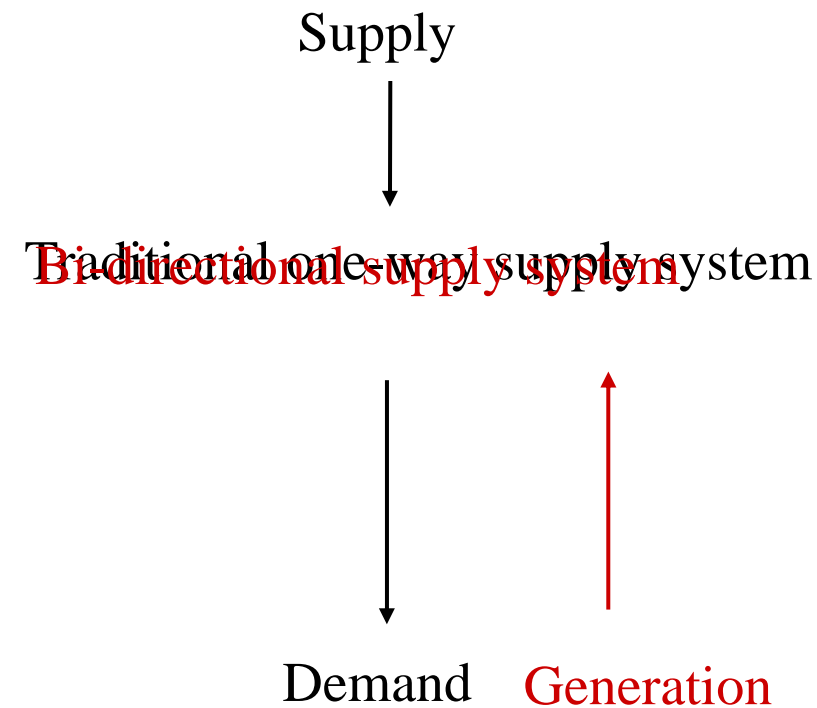
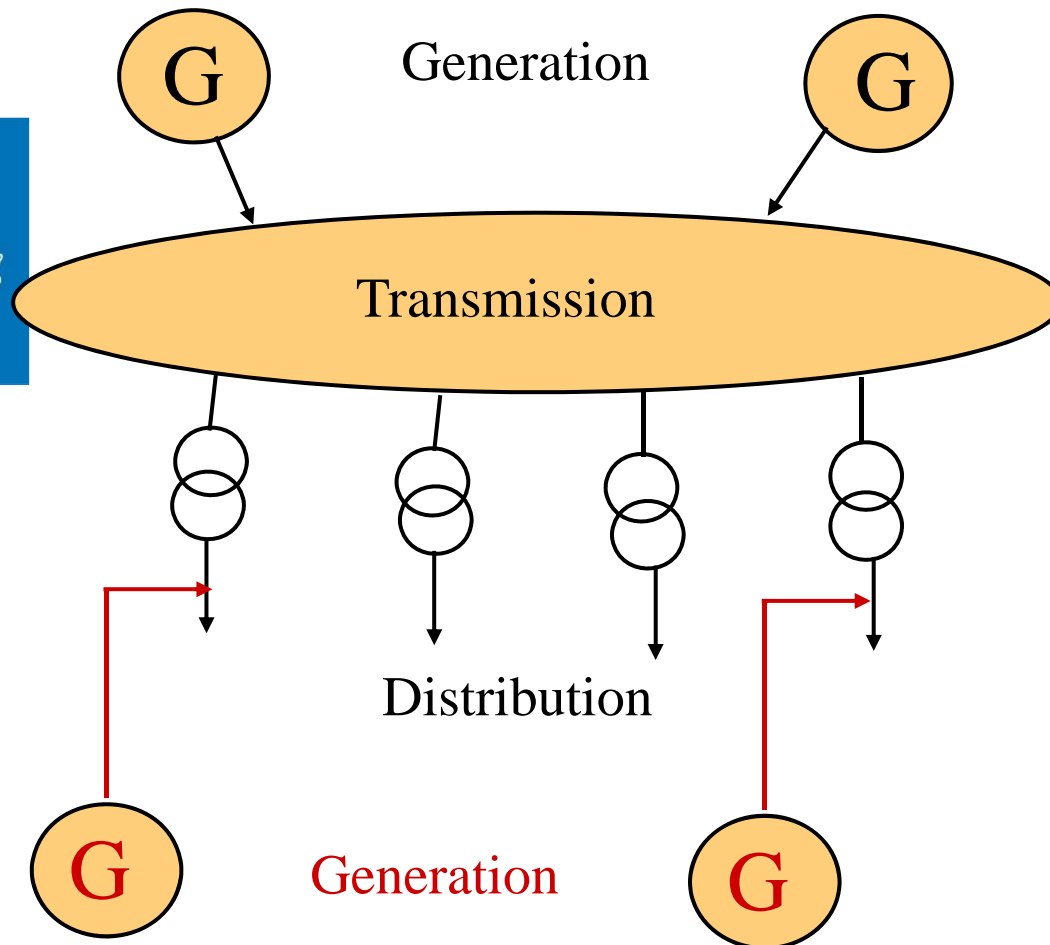
Computer Applications in  
Power Systems – Advance course

EH2750

# Change In Physical Structure of Power System (Danish example)



# Change in Control Structure



# New Trends in Power Systems

- **Distributed and local control**
- **A level of intelligence**
- **A shift from reactive to proactive mode**
- **Self-awareness and Intelligence**
  - **Intelligent Software Agents**



# What is an agent?

“An agent is an **encapsulated** computer system that is **situated** in some environment and can act **flexibly** and **autonomously** in that environment, to meet its **design objectives**”

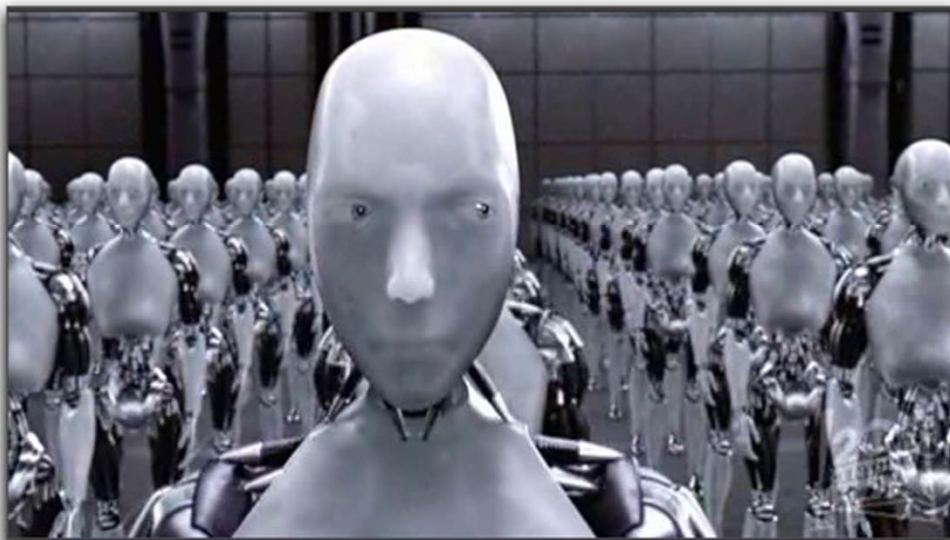


- Encapsulated
  - Metaphor
  - BDI
- Situated
  - Physical and Software (Virtual)
- Autonomous
- Flexible
  - Proactive
  - Social
- Design Objective (Goals\*)

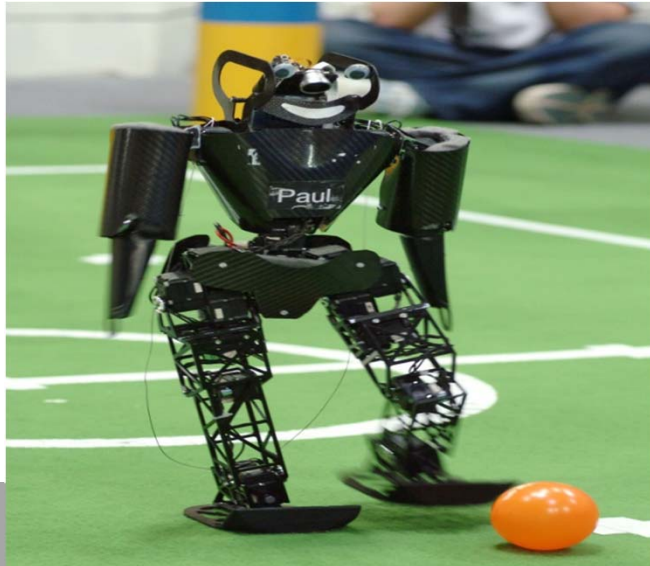
What does it all means -- What really an agent could be?



# Agent can be a Killing machine



# And Agents Can Be Built For Very Practical Purposes also





# Intelligent Agents



- An agent may also be able to:
  - communicate with other software agents
  - learn from experience
  - adapt to changes in the environment
  - make plans
  - reason using, e.g., logic or game theory
  - move between different computers, and/or
  - negotiate with other agents
- Which of these abilities that are implemented in a particular agent depend on its tasks and purpose

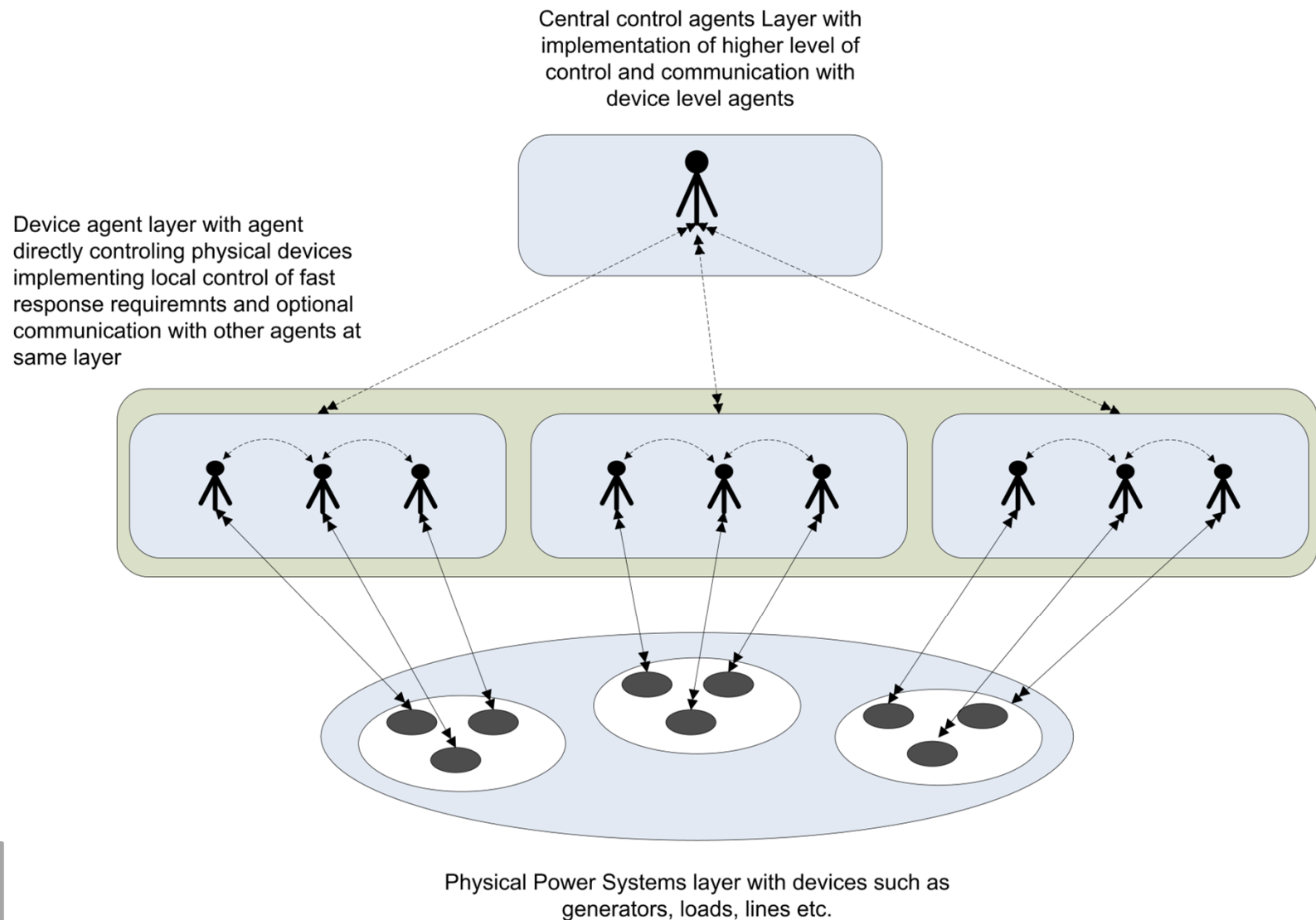


# Multi-agent System

“A Multi-Agent System (MAS) is a collection of agents co-operating or competing with each other in order to fulfill common or individual goals”



# Multiagent based distributed control



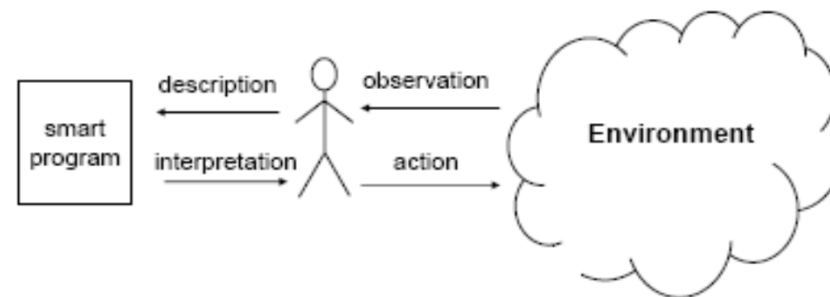
# Software vs. Physical Agents



- Software agents
  - situated in a software environment, e.g., operating systems and networks (Internet)
  - *simple example*: software demons (e-mail)
  - *advanced example*: "shopbots"
- Physical agents
  - situated in the physical reality
  - *simple example*: energy saving devices
  - *advanced example*: mobile robots

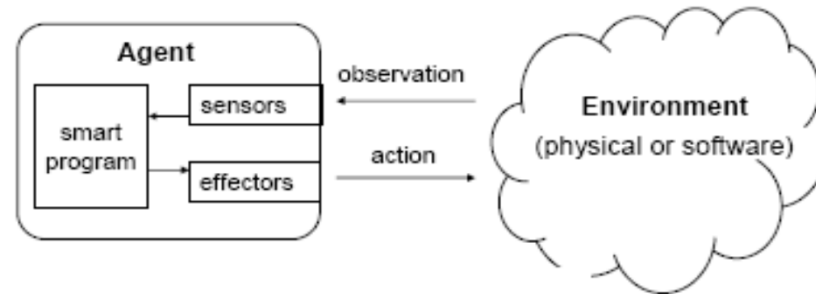
# Intelligent Agents vs. Expert Systems

- In expert systems there is a human present between program environment



# Intelligent Agents vs. Expert Systems

- Agent reside in the Environment and interacts with it directly (no interface is required)





# Agents Vs Objects

- **Agents natural extension\evolution of Objects BUT with some very fundamental differences**
  - **Level of Autonomy**
  - **Stronger design metaphor**
  - **High Level Interactions – Supporting Organizational structure**
  - **Proactively**
  - **Separate Thread of Execution – Independent life span**



# Agents Vs Objects



- It is about adding new abstraction entities:
  - OOP = structured programming + objects that have persistent local states
  - AOP = OOP + agents that have an independent execution thread + pro-activity + greater level of autonomy over itself
- An agent is able to act in a *goal-directed* fashion rather than just passively reacting to procedure calls
  - “An agent can say no!”

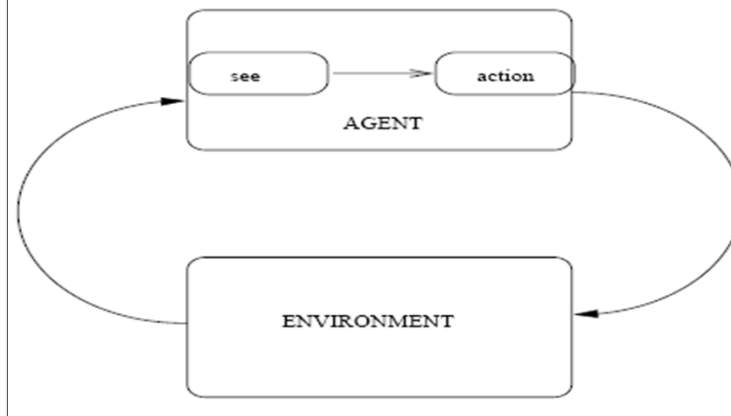
## Agents as intentional systems



- Agents are sometimes modeled, using "mental states", e.g.
  - *Beliefs*, what the agent knows (or think it knows)
  - *Desires*, the goals of the agent
  - *Intentions*, what the agent has decided to do OR how agent is going to achieve desires/intentions

# Purely reactive agents

- The simplest kind of agent, appropriate for simple tasks



- Input: sensor data and received messages
- Output: effector signals and sent messages
- The most basic reactive agents are specified by a set of independent situation-action rules.



# The subsumption architecture

- A hierarchy of behaviors where each behavior is a simple rule-like structure

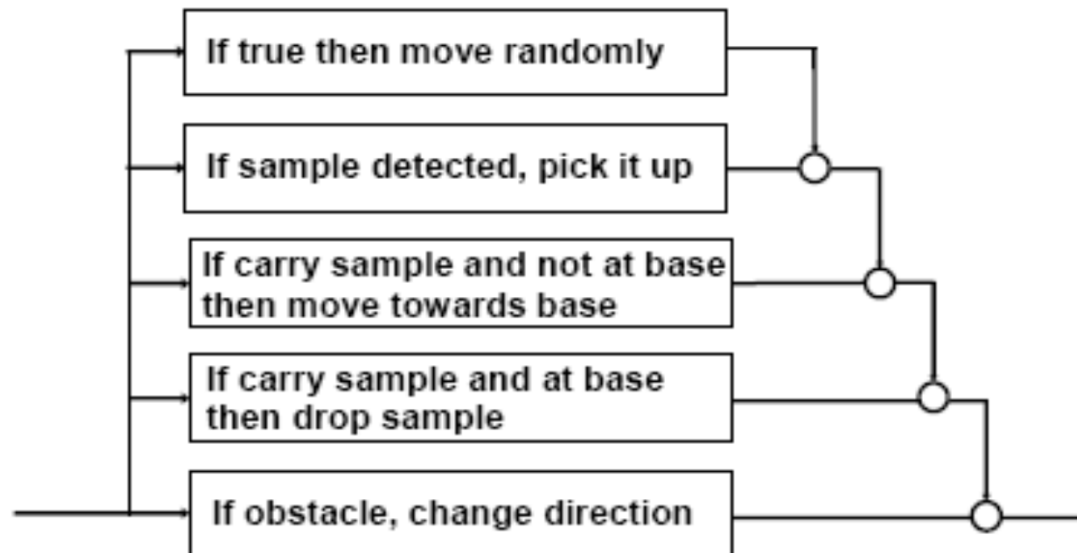


- The lower behaviors are the most basic and have precedence over higher behaviors
- Bottom-up methodology: start with the most basic behaviors and make them work first



# Example: planet exploration

- Task: collect samples of precious rocks



# Limitations of Reactive Agents



- Cannot perform tasks that require knowledge about the world that must be obtained by reasoning or from memory, e.g.
  - response to events beyond the agent's current sensory limits
  - learning from experience,
  - some amount of problem solving
  - prediction of other agents' behavior.
- Each behavior must be separately encoded, which may lead to complexity problems.

# Deliberative agents

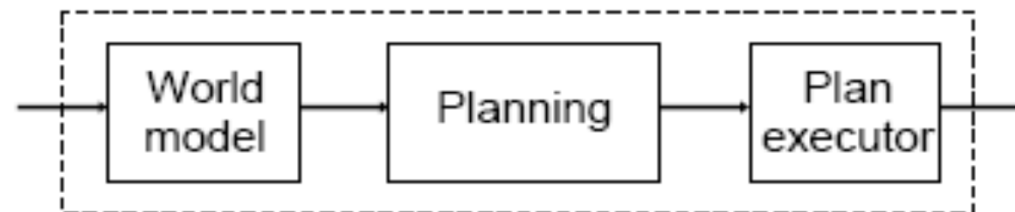


- Top-down methodology: begin with the overall architecture and then develop the different components separately.
- Ex. Planning (means-ends reasoning) agent:

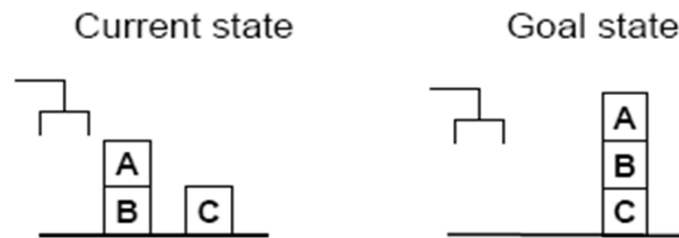
# Deliberative agents



- Top-down methodology: begin with the overall architecture and then develop the different components separately.
- Ex. Planning (means-ends reasoning) agent:



# A simple planner



- Possible actions:
  - pickup(What) and putdown(Where)
- Resulting plan:
  - pickup(A), putdown(table), pickup(B), putdown(C), pickup(A), putdown(B)
- Most of real world problems deals with finding a Plan(sequence of actions)



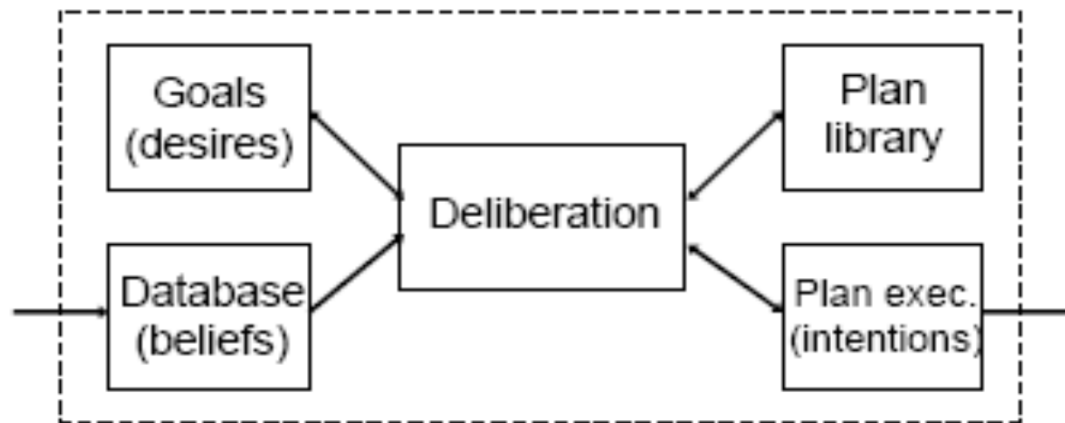
# Limitations of planning agents



- Typically, a plan is constructed by searching through the space of possible action sequences until one is found that will transform the current state into the goal state
- But this is very time-consuming (NP-complete)
- Requiring search through potentially enormous problem spaces
- The situation may change while the agent is constructing its plan, making it useless
- May be suitable for abstract tasks, but have problems with “simpler” concrete tasks that require fast reaction (but no deliberation)

# Procedural Reasoning System

- Use pre-compiled plans!

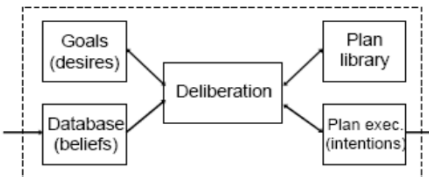


- The plans are not just a sequence of actions but can also contain [sub] Goals



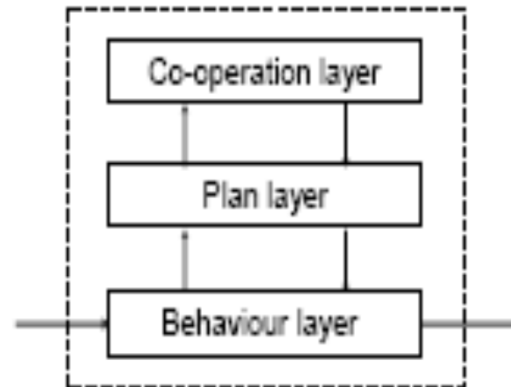
# Basic functionality of PRS

- A plan has three components
  - the goal: the post-condition
  - the context: the pre-conditions
  - the body: a sequence of actions and/or goals
- Simplified algorithm:
  - select a goal from Desires and push it to the Intention stack
  - while not Intention stack empty
    - pop the Intention stack
    - if it is an action, perform the action
    - if it is a goal, (and it's not already fulfilled) find a plan that matches the goal and push the body to the Intention stack



# Hybrid layered agents

- **Combines reactive and deliberative behavior**

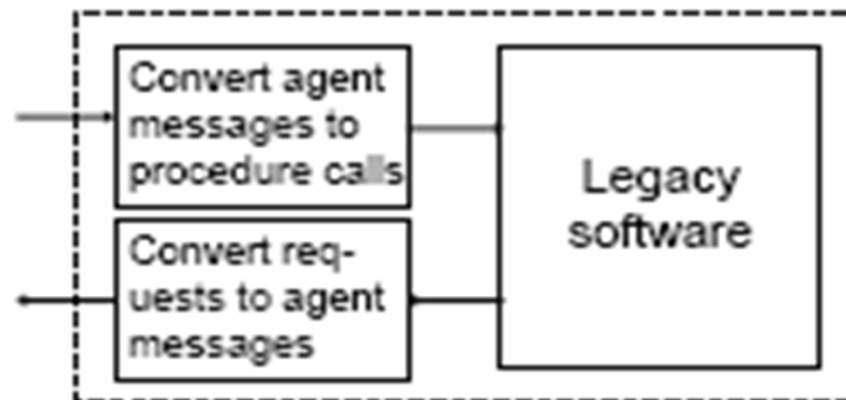


- A lower layer passes control to a higher layer when it is not competent to deal with the current situation.

# Wrapper agents



- An approach to "agentify" legacy software systems, such as, expert systems, database handlers, and control software
- The wrapping software makes the legacy code appear as a normal agent to other agents.





# Agent Communication Languages (ACLs)



- To interact effectively the agents need to be able to communicate with each other
- Most ACLs builds upon the *speech act theory*, which views language as *actions*.
- Examples: KQML and FIPA ACL
- They support a set of *performatives* that defines the permissible communicative operations that agents may attempt such as:
  - informing, asking questions, and commanding

# FIPA ACL message



```
(inform
  :sender agent1
  :receiver auction-server
  :content
    (price (bid good02)
  150)
  :in-reply-to round-4
  :reply-with bid04
  :language sl
  :ontology auction
```

)

# Sample KQML Message and Response



```
(ask-one
:sender student
:content
  'price(beer,Price)'
:receiver beer-server
:language Prolog
:ontology beer-bongs
)
```

```
(tell
:sender beer-server
:content 'price(beer,45)'
:receiver student
:language Prolog
:ontology beer-bongs
)
```

# Main arguments for choosing an agent based approach



- Methodology - new level of abstraction enables the implementation of more complex control strategies
- Robustness - often no critical single point of failure
- Efficiency - less complex computations
- Flexibility - ACLs supports complex interaction
- Scalability - easy to add new agents to a MAS

# When to use agents



- Modular - possible to identify distinct "entities"
- Decentralized - entities can perform useful tasks without continuous direction from some other entity
- Changeable - the structure of the system may change quickly and frequently
- Ill-structured - all information is not available when the system is being designed
- Complex - the system needs to exhibit a large number of different behaviors which may interact in sophisticated ways