



HE1011 Control Systems 7.5 credits

Reglersystem

This is a translation of the Swedish, legally binding, course syllabus.

If the course is discontinued, students may request to be examined during the following two academic years

Establishment

Course syllabus for HE1011 valid from Autumn 2007

Grading scale

A, B, C, D, E, FX, F

Education cycle

First cycle

Main field of study

Electrical Engineering, Technology

Specific prerequisites

Basic knowledge in mathematics (algebra, matrices, equation systems, differential equations and complex numbers)

Language of instruction

The language of instruction is specified in the course offering information in the course catalogue.

Intended learning outcomes

The course should provide basic understanding how processes and control systems can be interpreted in terms of differential equations. The participants should obtain a feeling for which factors determine the properties of a control system, such as stability, response speed and accuracy. The course also aims to acclimate to control systems simulation software.

After finishing the course, the students should be able to

- Describe processes and control systems using differential equations.
- Create block diagrams based on differential equations describing the system.
- Calculate parameters indicating different properties of the system, such as stability, response speed and accuracy.
- Simulate the behaviour of a control system using available software.
- Give account for the principles of different practical controllers, such as PID, fuzzy and pole positioning controllers.
- Give account for various methods of optimising mentioned controllers and, with regards to PID and pole positioning controllers, be able to carry out calculations using the optimisation methods.

Course contents

- Applying linear differential equations on processes involving mechanics, electronics, thermodynamics and hydraulics.
- Laplace transforms and transfer functions.
- Properties of analogue systems.
- Frequency analysis
- Simulation
- Dimensioning of analogue controllers
- Discrete-time controlling systems
- Z-transforms and transfer functions
- Properties of discrete-time systems
- Dimensioning of discrete-time controllers
- Basic fuzzy control

Course literature

Thomas, Bertil: Modern Reglerteknik, Liber, ISBN 91-47-05085-3

Thomas, Bertil: Modern Reglerteknik, Övningsbok, Liber, ISBN 91-47-05103-5

Examination

- LAB1 - Laboratory Work, 1.5 credits, grading scale: P, F
- TEN1 - Written examination, 6.0 credits, grading scale: A, B, C, D, E, FX, F

Based on recommendation from KTH's coordinator for disabilities, the examiner will decide how to adapt an examination for students with documented disability.

The examiner may apply another examination format when re-examining individual students.

Other requirements for final grade

Passed written exam (TEN1; 6 cr.), grading A-F

Passed practical exercises (LAB1; 1,5 cr.), grading P/F

Final grade A-F

Ethical approach

- All members of a group are responsible for the group's work.
- In any assessment, every student shall honestly disclose any help received and sources used.
- In an oral assessment, every student shall be able to present and answer questions about the entire assignment and solution.