



SF2832 Mathematical Systems Theory 7.5 credits

Matematisk systemteori

This is a translation of the Swedish, legally binding, course syllabus.

If the course is discontinued, students may request to be examined during the following two academic years

Establishment

Course syllabus for SF2832 valid from Spring 2011

Grading scale

A, B, C, D, E, FX, F

Education cycle

Second cycle

Main field of study

Mathematics

Specific prerequisites

In general:

150 university credits (hp) including 28 hp in Mathematics and 6 hp in Mathematical Statistics. Documented proficiency in English corresponding to English B.

More precisely for KTH students:

Passed courses in calculus, linear algebra, differential equations, mathematical statistics, numerical analysis. A passed course in control theory is an advantage.

Language of instruction

The language of instruction is specified in the course offering information in the course catalogue.

Intended learning outcomes

This is an introductory course in mathematical systems theory. The subject provides the mathematical foundation of modern control theory, with application in aeronautics, electrical networks, signal processing, and many other areas. The aim of the course is that you should acquire a systematic understanding of linear dynamical systems, which is the focus of this course. The acquirement of such knowledge is not only very useful preparation for work on system analysis and design problems that appear in many engineering fields, but is also necessary for further studies in control and signal processing.

The overall goal of the course is to provide an understanding of the basic ingredients of linear systems theory and how these are used in analysis and design of control, estimation and filtering systems. In the course we take the state-space approach, which is well suited for efficient control and estimation design.

Measurable goals:

To pass the course, the student should be able to do the following:

- Analyze the state-space model with respect to minimality, observability, reachability, detectability and stabilizability.
- Explain the relationship between input-output (external) models and state-space (internal) models for linear systems and derive such models from the basic principles.
- Derive a minimal state-space model using the Kalman decomposition.
- Use algebraic design methods for state feedback design with pole assignment, and construct stable state observers by pole assignment and analyze the properties of the closed loop system obtained when the observer and the state feedback are combined to an observer based controller.
- Apply linear quadratic techniques to derive optimal state feedback controllers.
- Design a Kalman filter for optimal state estimation of linear systems subject to stochastic disturbances.
- Solve the Riccati equations that appear in optimal control and estimation problems.
- Apply the methods given in the course to solve example problems (one should also be able to use the Control System Toolbox in Matlab to solve the linear algebra problems that appear in the examples).

To receive the highest grade, the student should in addition be able to do the following:

- Integrate the tools learnt during the course and apply them to more complex problems.
- Explain how the above results and methods relate and build on each other.

- Explain the mathematical (mainly linear algebra) foundations of the techniques used in linear systems theory and apply those techniques flexibly to variations of the problems studied in the course.
- Solve fairly simple but realistic control design problems using the methods in the course.

Course contents

Linear control systems: reachability, observability, stability, realization theory, minimality, feedback, pole-assignment, observers. Linear-quadratic optimal control, matrix Riccati equation and theory for the algebraic Riccati equation. Kalman filtering.

Course literature

Lindquist & Sand: An introduction to mathematical systems theory (Lecture notes)

Examination

- HEM1 - Assignments, - credits, grading scale: P, F
- TEN1 - Examination, 7.5 credits, grading scale: A, B, C, D, E, FX, F

Based on recommendation from KTH's coordinator for disabilities, the examiner will decide how to adapt an examination for students with documented disability.

The examiner may apply another examination format when re-examining individual students.

Other requirements for final grade

A written examination (TEN1; 7,5 hp).

Optional homework sets that give bonus credit on the exam.

Ethical approach

- All members of a group are responsible for the group's work.
- In any assessment, every student shall honestly disclose any help received and sources used.
- In an oral assessment, every student shall be able to present and answer questions about the entire assignment and solution.